

Chapter 4: QM in three dimensions

In principle, the generalization 1D to 3D is **simple**:

$$i\hbar \frac{\partial \Psi}{\partial t} = H\Psi = \left[\frac{1}{2m} (p_x^2 + p_y^2 + p_z^2) + V(x,y,z) \right] \Psi$$

where we follow the same **rules of 1D, but now in 3D**:

$$p_x \rightarrow \frac{\hbar}{i} \frac{\partial}{\partial x}, \quad p_y \rightarrow \frac{\hbar}{i} \frac{\partial}{\partial y}, \quad p_z \rightarrow \frac{\hbar}{i} \frac{\partial}{\partial z},$$

Written in a compact form we obtain:

$$\mathbf{p} \rightarrow \frac{\hbar}{i} \overset{\text{gradient operator}}{\nabla} \longrightarrow i\hbar \frac{\partial \Psi}{\partial t} = -\frac{\hbar^2}{2m} \nabla^2 \Psi + V \Psi$$

where the
Laplacian is:

$$\nabla^2 \equiv \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$$

The normalization in 3D is: $\int_{\mathbf{r}=(x,y,z)} |\Psi|^2 d^3\mathbf{r} = 1$

where in Cartesian coordinates $d^3\mathbf{r} = dx dy dz$

The **time independent**
Sch. Eq. is:

$$-\frac{\hbar^2}{2m}\nabla^2\psi + V\psi = E\psi$$

Solutions are the **stationary states**, or **eigenstates** of the Hamiltonian, with the **regular time dependence**:

$$\Psi_n(\mathbf{r}, t) = \psi_n(\mathbf{r})e^{-iE_nt/\hbar}$$

Any 3D wave function can be expanded similarly as in 1D, due to **completeness** and **orthonormality**:

$$\Psi(\mathbf{r}, t) = \sum_n c_n \psi_n(\mathbf{r}) e^{-iE_nt/\hbar}$$

Once again, **coordinates and momenta**
do not commute (i,j Cartesian coordinates x,y,z):

$$[r_i, p_j] = -[p_i, r_j] = i \hbar \delta_{ij} \quad , \quad [r_i, r_j] = [p_i, p_j] = 0$$

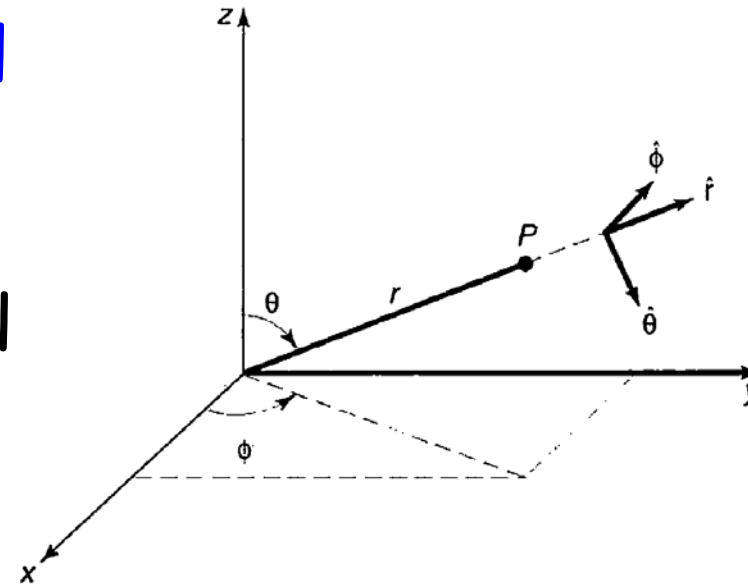
Once again, **expectation values behave**
like classical variables:

$$\frac{d}{dt} \langle \mathbf{r} \rangle = \frac{1}{m} \langle \mathbf{p} \rangle, \quad \text{and} \quad \frac{d}{dt} \langle \mathbf{p} \rangle = \langle -\nabla V \rangle$$

Once again, **there are uncertainty inequalities**:

$$\sigma_x \sigma_{p_x} \geq \hbar/2, \quad \sigma_y \sigma_{p_y} \geq \hbar/2, \quad \sigma_z \sigma_{p_z} \geq \hbar/2$$

4.1.1: However, **Spherical coordinates** is what we need for the Hydrogen atom because of rotational invariance:



The Laplacian in spherical coordinates is "complicated". Without a proof just accept that:

$$\nabla^2 = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \left(\frac{\partial^2}{\partial \phi^2} \right)$$

function of r only

function of r
and θ only

function of
r, θ, and φ

After this "complicated" Laplacian is used,
the Sch. Eq. becomes:

$$-\frac{\hbar^2}{2m} \left[\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial \psi}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial \psi}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \left(\frac{\partial^2 \psi}{\partial \phi^2} \right) \right] + V \psi = E \psi$$

How do we even start addressing this difficult diff. eq.? As usual, try first separation of variables between **radial** and **angular coordinates**:

Simplification:
In many cases of interest
 $V=V(r)$ only, like the H atom.

$$\psi(r, \theta, \phi) = R(r)Y(\theta, \phi)$$

Use the proposed solution in the Hamiltonian ...
and hope for the best:

$$-\frac{\hbar^2}{2m} \left[\frac{Y}{r^2} \frac{d}{dr} \left(r^2 \frac{dR}{dr} \right) + \frac{R}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial Y}{\partial \theta} \right) + \frac{R}{r^2 \sin^2 \theta} \frac{\partial^2 Y}{\partial \phi^2} \right] + VRY = ERY$$

Divide by $R(r)Y(\theta, \phi)$ and multiply all by $(-2mr^2/\hbar^2)$:

Only function of r : $\left\{ \frac{1}{R} \frac{d}{dr} \left(r^2 \frac{dR}{dr} \right) - \frac{2mr^2}{\hbar^2} [V(r) - E] \right\}$

Only function of angles θ and ϕ : $+\frac{1}{Y} \left\{ \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial Y}{\partial \theta} \right) + \frac{1}{\sin^2 \theta} \frac{\partial^2 Y}{\partial \phi^2} \right\} = 0.$

Because the sum of a term that depends on r and a term that depends on angles gives zero, **both must be constant and of opposite sign:**

$$\frac{1}{R} \frac{d}{dr} \left(r^2 \frac{dR}{dr} \right) - \frac{2mr^2}{\hbar^2} [V(r) - E] = l(l + 1);$$

$$\frac{1}{Y} \left\{ \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial Y}{\partial \theta} \right) + \frac{1}{\sin^2 \theta} \frac{\partial^2 Y}{\partial \phi^2} \right\} = -l(l + 1)$$

The angular component is more “fun” (physicists talking) and we will study that first. **It leads to all the weird shapes of orbitals. Plus, it is independent of $V(r)$ i.e. generic for many problems.**

Moving $Y(\theta, \phi)\sin^2(\theta)$ to the other side, we focus on the **4.1.2 Angular Equation** which is the SAME for any potential $V(r)$:

$$\sin \theta \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial Y}{\partial \theta} \right) + \frac{\partial^2 Y}{\partial \phi^2} = -l(l+1) \sin^2 \theta Y$$

Let us once again try separation of variables, followed by the canonical division by $\Theta\Phi$:

$$Y(\theta, \phi) = \Theta(\theta)\Phi(\phi)$$

$$\underbrace{\left\{ \frac{1}{\Theta} \left[\sin \theta \frac{d}{d\theta} \left(\sin \theta \frac{d\Theta}{d\theta} \right) \right] + l(l+1) \sin^2 \theta \right\}}_{\text{function of } \theta \text{ only}} + \underbrace{\frac{1}{\Phi} \frac{d^2 \Phi}{d\phi^2}}_{\text{function of } \phi \text{ only}} = 0$$

function of θ only
Total derivative notation used, instead of partial,
because unknown function depends only on θ

function of ϕ only

As in several occasions before, then this means:

$$\frac{1}{\Theta} \left[\sin \theta \frac{d}{d\theta} \left(\sin \theta \frac{d\Theta}{d\theta} \right) \right] + l(l+1) \sin^2 \theta = m^2$$

$$\frac{1}{\Phi} \frac{d^2 \Phi}{d\phi^2} = -m^2$$

Thus, up to now via the trick of the separation of variables we have managed to write the **single** huge Sch. Eq. in spherical coordinates, into **three** separated equations.

In doing so, we introduced three unknown constants **E** (energy of the stationary states that likely will have an index n for bound states), plus **$l(l+1)$** and **m** .

Thus, solutions will have **THREE** labels: **n, l, m** .
We say "three quantum numbers".

Fortunately, the equation for ϕ is easy!

$$\frac{d^2\Phi}{d\phi^2} = -m^2\Phi \Rightarrow \Phi(\phi) = e^{im\phi}$$

Because “physics” has to be the same after a 2π rotation then we impose:

$$\Phi(\phi + 2\pi) = \Phi(\phi)$$

which leads to **quantization of m** (discrete values):

$$m = 0, \pm 1, \pm 2, \dots$$

The second angular equation is NOT easy:

$$\sin \theta \frac{d}{d\theta} \left(\sin \theta \frac{d\Theta}{d\theta} \right) + [l(l+1) \sin^2 \theta - m^2] \Theta = 0$$

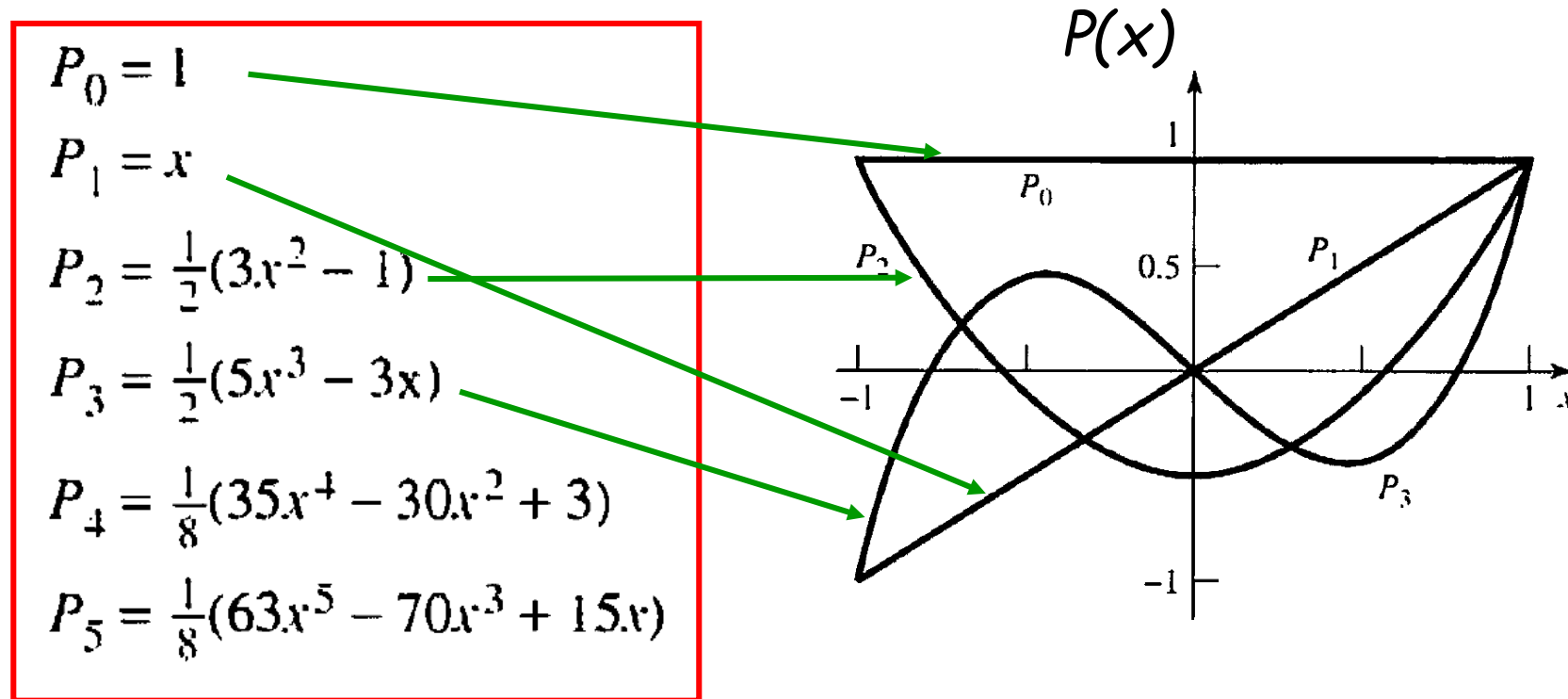
The solution is simply given to you:

$$\Theta(\theta) = A P_l^m(\cos \theta)$$

Called the **associated Legendre function** (not polynomials)

For $m=0$, they are just called the **Legendre polynomials** (yes, now polynomials).

These $m=0$ polynomials will be given to you. At most you will be asked to prove that indeed they are solutions. Using the very common notation $\cos(\theta) = x$:



These polynomials can be divided in even and odd.

But we need the **entire** associated Legendre functions (i.e. arbitrary m). Just accept the following formula:

$$P_l^m(x) \equiv (1 - x^2)^{|m|/2} \left(\frac{d}{dx} \right)^{|m|} P_l(x).$$

$l=2, m=0$

$l=2, m=1 \text{ or } -1$

$$P_2^0(x) = \frac{1}{2}(3x^2 - 1), \quad P_2^1(x) = (1 - x^2)^{1/2} \frac{d}{dx} \left[\frac{1}{2}(3x^2 - 1) \right] = 3x\sqrt{1 - x^2}.$$

$$P_2^2(x) = (1 - x^2) \left(\frac{d}{dx} \right)^2 \left[\frac{1}{2}(3x^2 - 1) \right] = 3(1 - x^2),$$

$l=2, m=2 \text{ or } -2$

Not a polynomial.
But note $(1 - x^2)$ is
simply $\sin^2(\theta)$!

Note that in the formula of previous page " l " is the order of the polynomial, thus if $|m| > l$, we obtain a zero after the derivatives are made.

$$P_l^m(x) \equiv (1 - x^2)^{|m|/2} \left(\frac{d}{dx} \right)^{|m|} P_l(x).$$

As a consequence we have the following constraints:

$$l = 0, 1, 2, \dots; \quad m = -l, -l + 1, \dots, -1, 0, 1, \dots, l - 1, l$$

For each integer " l ", there are $(2l+1)$ values of m .

All associated Legendre functions you may need will be given to you in exams (in HW you may have to look for them in tables or you may google them):

$$P_0^0 = 1$$

$$P_2^0 = \frac{1}{2}(3 \cos^2 \theta - 1)$$

$$P_1^1 = \sin \theta$$

$$P_3^3 = 15 \sin \theta (1 - \cos^2 \theta)$$

$$P_1^0 = \cos \theta$$

$$P_3^2 = 15 \sin^2 \theta \cos \theta$$

$$P_2^2 = 3 \sin^2 \theta$$

$$P_3^1 = \frac{3}{2} \sin \theta (5 \cos^2 \theta - 1)$$

$$P_2^1 = 3 \sin \theta \cos \theta$$

$$P_3^0 = \frac{1}{2} (5 \cos^3 \theta - 3 \cos \theta)$$

If you graph these functions, the “orbitals” that you have seen many times before since high school start appearing!

