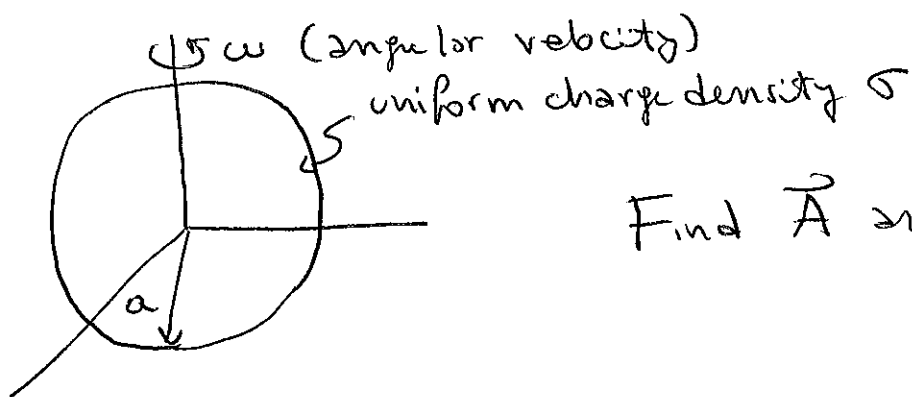


Problem 5.13



Find \vec{A} and \vec{B} .

The velocity \vec{v} at any point on the sphere is

A diagram showing a sphere with a vertical axis $\vec{\omega}$ and a position vector \vec{r} from the center to the surface. The resulting velocity vector \vec{v} is shown as a tangent to the sphere at that point. The angle between $\vec{\omega}$ and \vec{r} is θ .

$$\vec{v} = \vec{\omega} \times \vec{r} = \omega \times (\hat{\omega} \times \hat{r}) = \omega |\hat{\omega} \times \hat{r}| \sin \theta$$

$$|\hat{a} \times \hat{b}| = |\hat{a}| |\hat{b}| \sin \theta$$

Then, the surface ^{current} density is $\vec{K} = \sigma \vec{v} =$
 $= \sigma \omega a \sin \theta \hat{\phi}$

↑
Using notation of (5.87)

The charge exists only at the surface.
 Then, outside the surface $\vec{J} = 0$ and $\nabla \times \vec{H} = 0$
 and $\vec{H} = -\nabla \Phi_M$.

For $r < a$ we propose, following (3.33)

$$\Phi_M(r, \theta) = \sum_{l=0}^{\infty} A_l r^l P_l(\cos \theta)$$

For $r > a$, we also use (3.33)

$$\Phi_M(r, \theta) = \sum_{l=0}^{\infty} B_l r^{-(l+1)} P_l(\cos \theta)$$

At $r=a$, there are two boundary conditions (see (S.86) and (S.87)):

$$(\vec{B}_2 - \vec{B}_1) \cdot \vec{n}_{21} = 0$$

$$\vec{n}_{21} \times (\vec{H}_2 - \vec{H}_1) = \vec{K}$$

The first one says that the "r" component of \vec{B} is continuous:

$$-\mu_0 \left. \frac{\partial \Phi_M}{\partial r} \right|_a^{r < a} = -\mu_0 \left. \frac{\partial \Phi_M}{\partial r} \right|_a^{r > a}$$

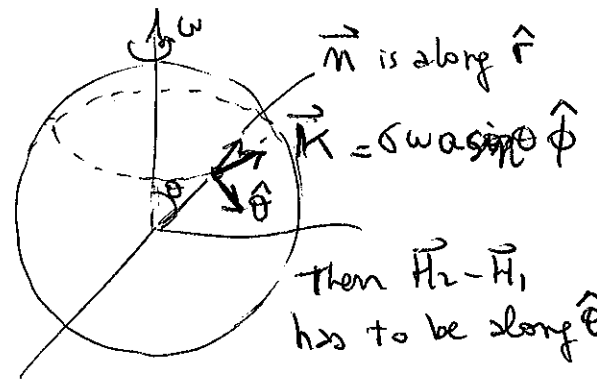
$$\leftarrow \vec{B} = \mu_0 \vec{H} = \mu_0 (-\nabla \Phi_M) \text{ but } \mu_0 \text{ drops.}$$

$$\sum_{l=0}^{\infty} A_l l a^{l-1} P_l(\cos \theta) = \sum_{l=0}^{\infty} B_l \frac{-(l-1)}{a^{l+2}} P_l(\cos \theta)$$

$$\text{or } \boxed{A_l l a^{l-1} = -\frac{(l-1) B_l}{a^{l+2}}}$$

The other equation says:

$$-\left[\left. \frac{1}{r} \frac{\partial \Phi_M}{\partial \theta} \right|_a^{r > a} - \left. \frac{1}{r} \frac{\partial \Phi_M}{\partial \theta} \right|_a^{r < a} \right] = \sigma_w \sin \theta$$



$$- \left[\frac{1}{a} \sum_{l=0}^{\infty} \frac{Bl}{a^{l+1}} \frac{\partial P_l(\cos \theta)}{\partial \theta} - \frac{1}{a} \sum_{l=0}^{\infty} Al a^l \frac{\partial P_l(\cos \theta)}{\partial \theta} \right] = \sigma \omega a \underbrace{\sin \theta}_{-\frac{\partial P_1(\cos \theta)}{\partial \theta}}$$

since $P_1(\cos \theta) = \cos \theta$

Then:

$$\boxed{-\frac{1}{a} \frac{Bl}{a^{l+1}} + \frac{1}{a} Al a^l = -\sigma \omega a S_{l1}}$$

Consider $l \neq 1$ first. Then:

$$Al a^{l-1} = -\frac{(l+1)Bl}{a^{l+2}} \quad \text{or} \quad Al a^{l-1} = -\frac{(l+1)}{l} \frac{Bl}{a^{l+2}}$$

$$\frac{Al a^l}{a} = \frac{Bl}{a^{l+2}} \quad \text{or} \quad Al a^{l+1} = \frac{Bl}{a^{l+2}} \rightarrow \text{incompatible}$$

The only solution is $\boxed{Al = Bl = 0 \text{ for } l \neq 1}$.

Consider now $l=1$:

$$A_1 = -\frac{2B_1}{a^3}$$

$$-\frac{B_1}{a^3} + A_1 = -\sigma \omega a$$

or $A_1 = +2(-\sigma \omega a - A_1) \rightarrow 3A_1 = -2\sigma \omega a$

$$\boxed{A_1 = -\frac{2\sigma \omega a}{3}}$$

$$B_1 = -\frac{a^3}{2} A_1 = -\frac{a^3}{2} \left(-\frac{2\sigma\omega a}{3} \right) = \boxed{\frac{1}{3} \sigma\omega a^4}$$

Then:

$$\Phi(r, \theta) = -\frac{2\sigma\omega a}{3} r \cos\theta \quad r < a$$

$$\Phi(r, \theta) = \frac{1}{3} \sigma\omega a^4 \frac{1}{r^2} \cos\theta \quad r > a$$

We can get \vec{H} via $\vec{H} = -\nabla\Phi_M = \mu_0^{-1} \vec{B}$

$$\vec{B} = \mu_0 (-\nabla\Phi_M) = \mu_0 \left[-\frac{\partial\Phi_M}{\partial r} \hat{r} - \frac{1}{r} \frac{\partial\Phi_M}{\partial\theta} \hat{\theta} \right] =$$

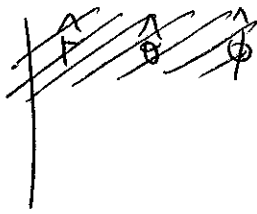
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back cover
of book, no ϕ dependence.

$$= \begin{cases} -\mu_0 \left[\left(-\frac{2\sigma\omega a}{3} \right) \cos\theta \hat{r} + \frac{1}{r} \left(\frac{2\sigma\omega a}{3} \right) r (-\sin\theta) \hat{\theta} \right] & r < a \\ -\mu_0 \left[\left(\frac{1}{3} \sigma\omega a^4 \right) \left(-\frac{2}{r^3} \right) \cos\theta \hat{r} + \frac{1}{r^3} \left(\frac{1}{3} \sigma\omega a^4 \right) \frac{1}{r^2} (-\sin\theta) \hat{\theta} \right] & r > a \end{cases}$$

$$= \begin{cases} \frac{2\sigma\omega a \mu_0}{3} \underbrace{(\cos\theta \hat{r} + \sin\theta \hat{\theta})}_{\hat{k}} & r < a \\ \frac{2\sigma\omega a^4 \mu_0}{3} \left(\frac{1}{r^3} \cos\theta \hat{r} + \frac{1}{2} \frac{\sin\theta}{r^3} \hat{\theta} \right) & r > a \end{cases}$$

Now we have to find \vec{A} . We can use $\nabla \times \vec{A} = \vec{B}$.
 We know that \vec{A} is along $\hat{\phi}$, by symmetry.

Then:



From back cover of book, we know $\nabla \times \vec{A}$ in spherical coordinates. Use $A_1 = A_2 = 0$ (which means $A_r = A_\theta = 0$) and you arrive to:

$$\nabla \times \vec{A} = \nabla \times (A_\phi \hat{\phi}) = \hat{e}_r \frac{1}{r \sin \theta} \frac{\partial (\sin \theta A_\phi)}{\partial \theta} - \frac{1}{r} \frac{\partial (r A_\phi)}{\partial r} \hat{e}_\theta$$

Then, for $r < a$ we have to find a A_ϕ such that

$$\frac{1}{r \sin \theta} \frac{\partial (\sin \theta A_\phi)}{\partial \theta} = \frac{2\sigma \omega a \mu_0 \cos \theta}{3}$$

and

$$-\frac{1}{r} \frac{\partial (r A_\phi)}{\partial r} = -\frac{2\sigma \omega a \mu_0 \sin \theta}{3}$$

By inspection $A_\phi = \frac{\mu_0 \sigma \omega a}{3} r \sin \theta$ ($r < a$)

check

$$\left\{ \begin{aligned} -\frac{1}{r} \frac{\partial (r A_\phi)}{\partial r} &= -\frac{1}{r} \frac{\partial (r^2 \sin \theta) \left(\frac{\mu_0 \sigma \omega a}{3} \right)}{\partial r} = -\frac{2r \sin \theta}{r} \frac{\mu_0 \sigma \omega a}{3} = \frac{\mu_0 \sigma \omega a}{3} = B_\theta \quad (r < a) \quad \checkmark \\ \frac{1}{r \sin \theta} \frac{\partial (\sin \theta \left(\frac{\mu_0 \sigma \omega a}{3} \right) r \sin \theta)}{\partial \theta} &= \frac{\mu_0 \sigma \omega a}{3} \frac{1}{\sin \theta} \frac{\partial \sin^2 \theta}{\partial \theta} = \frac{2}{3} \mu_0 \sigma \omega a \cos \theta = B_r \quad (r < a) \quad \checkmark \end{aligned} \right.$$

For $r > a$,

$$A\phi = \frac{\mu_0 \sigma \omega a^4 \sin\theta}{3r^2}$$

Check:

$$\left\{ \begin{aligned} -\frac{1}{r} \frac{\partial}{\partial r} (r A\phi) &= -\frac{1}{r} \frac{\mu_0 \sigma \omega a^4 \sin\theta}{3} \frac{\partial}{\partial r} \left(\frac{1}{r} \right) = + \frac{\mu_0 \sigma \omega a^4 \sin\theta}{3r^3} \quad \checkmark \\ &\quad \underbrace{\qquad\qquad\qquad}_{\frac{1}{r^2}} \quad \underbrace{\qquad\qquad\qquad}_{\text{Br for } r > a} \end{aligned} \right.$$

$$\left\{ \begin{aligned} \frac{1}{r \sin\theta} \frac{\partial}{\partial \theta} (\sin\theta A\phi) &= \frac{1}{r \sin\theta} \frac{\partial}{\partial \theta} \left(\sin\theta \frac{\mu_0 \sigma \omega a^4 \sin\theta}{3r^2} \right) = \\ &= \frac{\mu_0 \sigma \omega a^4}{3r^3} \frac{1}{\sin\theta} \frac{\partial}{\partial \theta} \sin^2\theta = \frac{2}{3} \frac{\mu_0 \sigma \omega a^4 \cos\theta}{r^3} \quad \checkmark \\ &\quad \underbrace{\qquad\qquad\qquad}_{2 \sin\theta \cos\theta} \quad \underbrace{\qquad\qquad\qquad}_{\text{Br for } r > a} \end{aligned} \right.$$