

5.8 Macroscopic Equations, Boundary Conditions

) We want to connect the "micro" with the "macro" descriptions.

First, note that $\nabla \cdot \vec{B} = 0$ is always valid, even at microscopic level. Then, at macro level too:

$$\boxed{\nabla \cdot \vec{B} = 0}$$

This means we can talk about a vector potential $\vec{A}(\vec{x})$ even in the presence of matter.

) The many molecular magnetic moments \vec{m}_i produce in average a macroscopic magnetization

$$\vec{M}(\vec{x}) = \sum_i N_i \langle \vec{m}_i \rangle$$

↙ average of \vec{m}_i per small volume at point \vec{x}
↘ # of molecules in small volume
Something like a "unit cell"

) Of course, we can also have in the system a macroscopic current density $\vec{J}(\vec{x})$.

This magnetic moment can have any origin, including the intrinsic spin of the electrons.

Overall:

keeping only the magnetic dipole moment

similar to (4.30) but for currents

$$\vec{A}(\vec{x}) \equiv \frac{\mu_0}{4\pi} \int \left[\frac{\vec{J}(\vec{x}')}{|\vec{x}-\vec{x}'|} + \frac{\vec{M}(\vec{x}') \times (\vec{x}-\vec{x}')}{|\vec{x}-\vec{x}'|^3} \right] d^3x'$$

This is using (5.55) and shifting coordinates.

Like done before when deriving (4.31), particularly using page 29 (bottom Eq.) we get:

$$\vec{A}(\vec{x}) = \frac{\mu_0}{4\pi} \int \left[\frac{\vec{J}(\vec{x}')}{|\vec{x}-\vec{x}'|} + \left(\vec{M}(\vec{x}') \times \nabla' \left(\frac{1}{|\vec{x}-\vec{x}'|} \right) \right) \right] d^3x'$$

Now we use a vector identity:

~~∇ × (ψA) = ψ(∇ × A) + (∇ψ) × A~~

$$\nabla \times (\psi \vec{A}) = \psi (\nabla \times \vec{A}) + \underbrace{(\nabla \psi) \times \vec{A}}_{-\vec{A} \times (\nabla \psi)}$$

Consider $\psi = \frac{1}{|\vec{x}-\vec{x}'|}$, $\vec{A} = \vec{M}(\vec{x}')$. Then: $-\vec{A} \times (\nabla \psi)$

$$\vec{M} \times \nabla' \left(\frac{1}{|\vec{x}-\vec{x}'|} \right) = - \nabla' \left(\frac{1}{|\vec{x}-\vec{x}'|} \right) \times \vec{M}$$

$$= - \nabla' \times \left(\frac{\vec{M}}{|\vec{x}-\vec{x}'|} \right) + \frac{1}{|\vec{x}-\vec{x}'|} (\nabla' \times \vec{M}(\vec{x}'))$$

The integral of the first term cancels

$$\int \nabla \times \left(\frac{\vec{M}(\vec{x}')}{|\vec{x} - \vec{x}'|} \right) d^3x'$$

Since it reduces to a surface integral which vanishes if all functions are "well behaved" and localized.

Stokes theorem

$$\int_V \nabla \times \vec{F} \cdot d\vec{S} = \oint_S \vec{F} \cdot d\vec{S}$$

then:

$$\vec{A}(\vec{x}) = \frac{\mu_0}{4\pi} \int \left(\frac{\vec{J}(\vec{x}')}{|\vec{x} - \vec{x}'|} + \frac{[\nabla' \times \vec{M}(\vec{x}')] }{|\vec{x} - \vec{x}'|} \right) d^3x' \quad (5.78)$$

Thus, it is as if the macroscopic medium provides an effective current density $\frac{\nabla' \times \vec{M}(\vec{x}')}{|\vec{x} - \vec{x}'|}$.
that includes

If \vec{A} is like (5.32), which was derived in free space, by just replacing \vec{J} by \vec{J}_{eff} , then (5.26) will also hold if $\vec{J} \rightarrow \vec{J}_{\text{eff}}$.

Then:

$$\nabla \times \vec{B} = \mu_0 \left[\vec{J} + \nabla \times \vec{M} \right] \quad (5.80)$$

\vec{J}_{eff}

If \vec{B} and \vec{M} are combined so

$$\vec{H} = \frac{\vec{B}}{\mu_0} - \vec{M}$$

← analogous to \vec{D} in electrostatics

then

$$\nabla \times \vec{H} = \nabla \times \left(\frac{\vec{B}}{\mu_0} \right) - \nabla \times \vec{M} = \vec{J} \quad (5.80)$$

(depends on sources \vec{J})
real

$$\nabla \times \vec{H} = \vec{J} \quad (5.82)$$

↑ not effective but "external" or "free"

and

$$\nabla \cdot \vec{B} = 0$$

names:
 B = magnetic induction
 H = magnetic field

As in the case of electrostatics, to complete the set of formulas for calculations we need a relation between \vec{H} and \vec{B} . Assuming linearity

and isotropy

$$\vec{B} = \mu \vec{H}$$

↑ magnetic permeability

The boundary conditions at an interface are:

From $\nabla \cdot \vec{B} = 0$, the integral over a ~~small~~ volume V

$$\int_V \nabla \cdot \vec{B} \, d^3x' = 0 \text{ of course.}$$

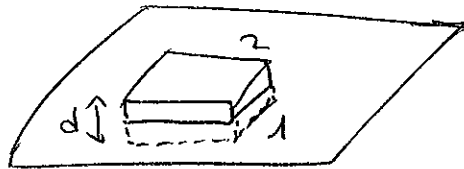


But this is $\oint_{\text{Surface}} \vec{B} \cdot \vec{n} \, da$ due to divergence theorem.

Then:

$$\oint_{\text{Surface}} \vec{B} \cdot \vec{n} \, da = 0$$

Now, apply this to a small volume at the interface as



As $d \rightarrow 0$, the only integrals that matter are the top and bottom ones. They become:

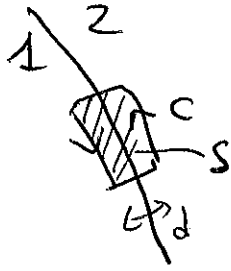
$$\boxed{(\vec{B}_2 - \vec{B}_1) \cdot \vec{n} = 0} \quad (5.86)$$

(See I.5 for details)

Now consider a small loop as in Fig I.4

We deduced

$$\nabla \times \vec{H} = \vec{J} \quad (5.82)$$



Apply now Stokes theorem

$$\int_S (\nabla \times \vec{F}) \cdot d\vec{a} = \int_{\partial S} \vec{F} \cdot d\vec{s}$$

$$\int_S \nabla \times \vec{H} \cdot d\vec{a} = \oint_C \vec{H} \cdot d\vec{l} = \int_S \vec{J} \cdot d\vec{a} = K \cdot \vec{t}$$

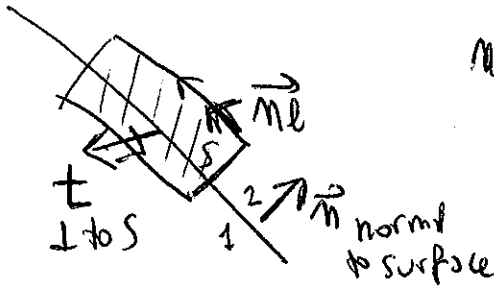
"side" contributions vanish as "d" → 0

"Surface current"
 \vec{t} = unit vector tangential to surface (points in same direction as $d\vec{a}$)
 (units of K) are (units of J) x area.

Then, we get:

$$(\vec{H}_2 - \vec{H}_1) \cdot \vec{n}_l = K \cdot \vec{t}$$

unit vector ~~is~~ shown. Note that $\vec{n}_l = \vec{t} \times \vec{m}$



$$(\vec{H}_2 - \vec{H}_1) \cdot (\vec{t} \times \vec{m}) = K \cdot \vec{t} = \vec{t} \cdot K$$

$$\vec{a} \cdot (\vec{b} \times \vec{c}) = \vec{c} \cdot (\vec{a} \times \vec{b}) = \vec{b} \cdot (\vec{c} \times \vec{a})$$

Then

$$\vec{E} \cdot (\vec{n} \times (\vec{H}_2 - \vec{H}_1)) = \vec{E} \cdot \vec{K}$$

\uparrow \uparrow \uparrow
"b" "c" "a"

Then

$$\vec{n} \times (\vec{H}_2 - \vec{H}_1) = \vec{K} \quad (S.87)$$

\vec{n} points from 1 to 2 i.e. it is \vec{n}_{12} .

Alternatively, using $\vec{B} = \mu \vec{H}$,

$$\vec{B}_2 \cdot \vec{n} = \vec{B}_1 \cdot \vec{n} \text{ becomes } \mu_2 \vec{H}_2 \cdot \vec{n} = \mu_1 \vec{H}_1 \cdot \vec{n}$$

and

$$\vec{n} \times \left(\frac{\vec{B}_2}{\mu_2} - \frac{\vec{B}_1}{\mu_1} \right) = \vec{K}$$

S.9 How do we solve these problems?

Basically we need to solve

$$\nabla \cdot \vec{B} = 0, \quad \nabla \times \vec{H} = \vec{J}$$

with some relation between \vec{B} and \vec{H} ; $\vec{H} = \vec{H}(\vec{B})$

(A) Always we can say $\vec{B} = \nabla \times \vec{A}$

plus $\nabla \times \vec{H}(\nabla \times \vec{A}) = \vec{J}$

and there are then equations in \vec{A} only.

For linear media, $\vec{B} = \mu \vec{H}$, and then

$$\nabla \times \left(\frac{\nabla \times \vec{A}}{\mu} \right) = \vec{J}$$

If μ is constant in some region, then in that

$$\frac{1}{\mu} \nabla \times (\nabla \times \vec{A}) = \frac{1}{\mu} (\nabla (\nabla \cdot \vec{A}) - \nabla^2 \vec{A}) = \vec{J}$$

Choosing $\nabla \cdot \vec{A} = 0$, then $-\nabla^2 \vec{A} = \mu \vec{J}$

Of course, in addition we have to deal with boundary conditions.

(B). $\vec{J} = \vec{0}$; Magnetic Scalar potential

If in some region $\vec{J} = \vec{0}$, then $\nabla \times \vec{H} = \vec{0}$ and \vec{H} can be written as $\vec{H} = -\nabla \Phi_M$ (similarly as $\vec{E} = -\nabla \phi$)

If the medium is linear then:

$$\nabla \cdot \vec{B} = \nabla \cdot (\mu \vec{H}) = -\nabla \cdot (\mu \nabla \Phi_M) = 0$$

If μ is "piecewise constant", then

$$\nabla^2 \Phi_M = 0 \text{ in each region}$$

[Typical example:
medium in uniform
external magnetic field]

(C) Hard Ferromagnets

Here a \vec{M} that is considered fixed, i.e. independent of applied fields. We will also assume $\vec{J} = \vec{0}$.

(a) We will use (B) above since $\vec{J} = \vec{0}$.

$$\nabla \cdot \vec{B} \stackrel{\uparrow}{=} \nabla \cdot (\mu_0 (\vec{H} + \vec{M})) = 0$$

(5.81)

In addition (B) says $\vec{H} = -\nabla\Phi_M$. Then
↑ if no currents

$$\nabla \cdot (\mu_0 (-\nabla\Phi_M) + \vec{M}) = 0$$

↑ ~~assumed piecewise const.~~
always constant, thus I drop it.

$$\cancel{\#} [-\nabla^2\Phi_M] + \nabla \cdot \vec{M} = 0$$

$$+\nabla^2\Phi_M = -\rho_M \stackrel{\text{def.}}{=} \frac{+\nabla \cdot \vec{M}}{\cancel{\#}}$$

From previous experience in electrostatics:

$$\Phi_M = -\frac{1}{4\pi} \int \frac{[\nabla' \cdot \mathbf{M}(\vec{x}')] d^3x'}{|\vec{x} - \vec{x}'|}$$

since

$$\nabla^2\Phi_M = -\frac{1}{4\pi} \int [\nabla' \cdot \mathbf{M}(\vec{x}')] \underbrace{\nabla^2 \left(\frac{1}{|\vec{x} - \vec{x}'|} \right)}_{-4\pi\delta(\vec{x} - \vec{x}')} d^3x' =$$

$$= \nabla \cdot \mathbf{M}(\vec{x}) \quad \checkmark$$

If \vec{M} is "well-behaved and localized", then we can integrate by parts as often many times before:

$$\nabla' \cdot (f \vec{A}) = \nabla' f \cdot \vec{A} + f (\nabla' \cdot \vec{A})$$

$$\underbrace{\int \nabla' \cdot (f \vec{A})}_{\rightarrow 0} = \underbrace{\int (\nabla' f \cdot \vec{A})}_{\vec{A} \cdot \nabla' f} + \int f (\nabla' \cdot \vec{A})$$

$$\text{Thus: } \int f (\nabla' \cdot \vec{A}) = - \int \vec{A} \cdot \nabla' f$$

Then, using $\vec{A} = \vec{M}$ and $f = \frac{1}{|\vec{x} - \vec{x}'|}$

$$\begin{aligned} \Phi_M &= + \frac{1}{4\pi} \int \vec{M}(\vec{x}') \cdot \underbrace{\nabla' \left(\frac{1}{|\vec{x} - \vec{x}'|} \right)}_{-\nabla \left(\frac{1}{|\vec{x} - \vec{x}'|} \right)} d^3x' = \\ &= - \frac{1}{4\pi} \nabla \cdot \int \frac{\vec{M}(\vec{x}')}{|\vec{x} - \vec{x}'|} d^3x' \end{aligned} \quad (5.98)$$

If there are no boundary surfaces!

Let us now assume "hard" ferromagnets:
 $M(\vec{x})$ inside a volume V and 0 outside.

Then, in this case there is a surface charge density σ_M . Then, the solution will be the one before plus the analog of (1.23) for magnets electrostatics. We need to find the value of σ_M . The value can be obtained similarly as the derivation of (4.46)

Remember
 $\rho_M = -\nabla \cdot \vec{M}$
 discontinuous
 thus $\frac{\partial M}{\partial n} = \int_{\text{surface}}$
 Then:

$$\sigma_M = \vec{n} \cdot \vec{M}$$



$$\sigma = -(\vec{P}_2 - \vec{P}_1) \cdot \vec{n}_{21}$$

Use $\vec{P}_2 = 0$
 $\vec{P}_1 = \vec{M}$
 $\vec{n}_{21} = \vec{n}$

$$\Phi_M(\vec{x}) = -\frac{1}{4\pi} \int_V \frac{[\nabla' \cdot \vec{M}(\vec{x}')] d^3x'}{|\vec{x} - \vec{x}'|} + \frac{1}{4\pi} \oint_S \frac{\vec{n}' \cdot \vec{M}(\vec{x}') da'}{|\vec{x} - \vec{x}'|} \quad (5.100)$$

We leave method C. (b) "vector potential" for the readers to discuss.
 (students)