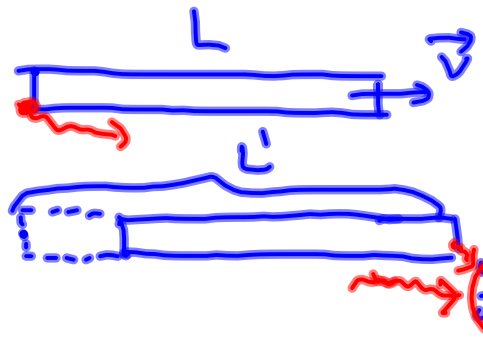


$$V(\vec{r}, t) = \frac{1}{4\pi\epsilon_0 |\vec{r}|} \underbrace{\int \rho(\vec{r}', t) d^3r'}_{\neq Q} \quad \begin{array}{l} \vec{r} = \vec{r} - \vec{w}(t) \\ \hat{n}, \hat{r} \\ |\vec{r}| = r, r = |\vec{r}| \end{array}$$

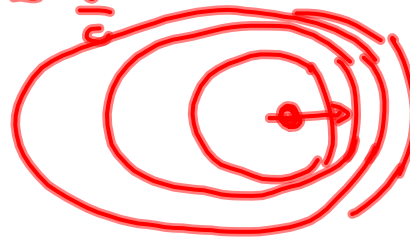
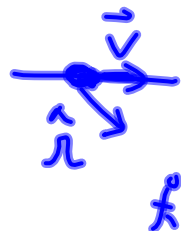


$$\left. \begin{array}{l} L' = L + vt \\ L' = ct \end{array} \right\} \frac{L'}{c} = \frac{L' - L}{v} = t$$

$$L' = \frac{L}{1 - \frac{v}{c}}$$

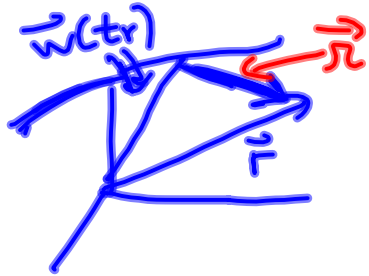
indep. of L
indep. of the
actual position

$$Q_{app} = L' \frac{Q}{L} = \frac{Q}{1 - \frac{v}{c}}$$



$$\frac{1}{1 - \frac{\hat{n} \cdot \vec{v}}{c}}$$

$$\underline{V(\vec{r}, t)} = \frac{q}{4\pi\epsilon_0 |\vec{r}|} \frac{1}{\left(1 - \frac{\hat{r} \cdot \vec{v}}{c}\right)} \xrightarrow{|\vec{v}| \rightarrow 0} \frac{q}{4\pi\epsilon_0 r}$$



$$\underline{\vec{A}(\vec{r}, t)} \stackrel{\rho \vec{v}}{=} \frac{\vec{v}(t_r)}{c^2} V(\vec{r}, t) \xrightarrow{|\vec{v}| \rightarrow 0} 0$$

$$\vec{E} = -\nabla V - \frac{\partial \vec{A}}{\partial t} \quad ; \quad \vec{B} = \nabla \times \vec{A}$$

Example 10.3

$$\vec{W} = \vec{V} t$$

$$n|\vec{n}| = |\vec{r} - \vec{w}|$$

$\hat{L}_{\vec{w}}(t_r)$

$\downarrow$ constant

$$|\vec{r} - \vec{w}| = |\vec{r} - \vec{V} t_r| = c(t - t_r)$$

$$|\vec{r} - \vec{V} t_r|^2 = c^2(t - t_r)^2$$

$$\underbrace{r^2} - 2\underbrace{\vec{r} \cdot \vec{V}} + \underbrace{V^2 t_r^2} = c^2(\underbrace{t^2} + 2t\underbrace{t_r} + \underbrace{t_r^2})$$

$$t_r = \frac{r}{c} \pm \sqrt{\dots}$$

$$\nabla t_r \neq 0$$

$$\nabla t = 0$$

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$$\nabla t_r = \frac{-\vec{n}}{nc - \vec{n} \cdot \vec{V}}$$

$$\nabla V = \nabla \left[\frac{q_c}{4\pi\epsilon_0 (\lambda c - \vec{\lambda} \cdot \vec{v})} \right] = \frac{q_c}{4\pi\epsilon_0} \left[-\frac{1}{(\lambda c - \vec{\lambda} \cdot \vec{v})^2} \right] \nabla (\lambda c - \vec{\lambda} \cdot \vec{v})$$

$$\nabla(\lambda c) = c \nabla \lambda = c \nabla [c(t - t_r)] = -c^2 \nabla t_r \neq 0$$

$$\nabla(\vec{\lambda} \cdot \vec{v})$$

$$\frac{\partial}{\partial x} \vec{v}(t_r) = \frac{\partial \vec{v}}{\partial t_r} \frac{\partial t_r}{\partial x}$$

$\vec{a}(t_r)$

$$\frac{\partial}{\partial t} \vec{A}(\vec{r}, t)$$

$$\nabla \times \vec{A}(\vec{r}, t)$$

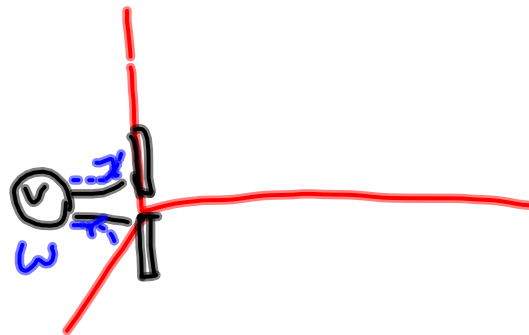
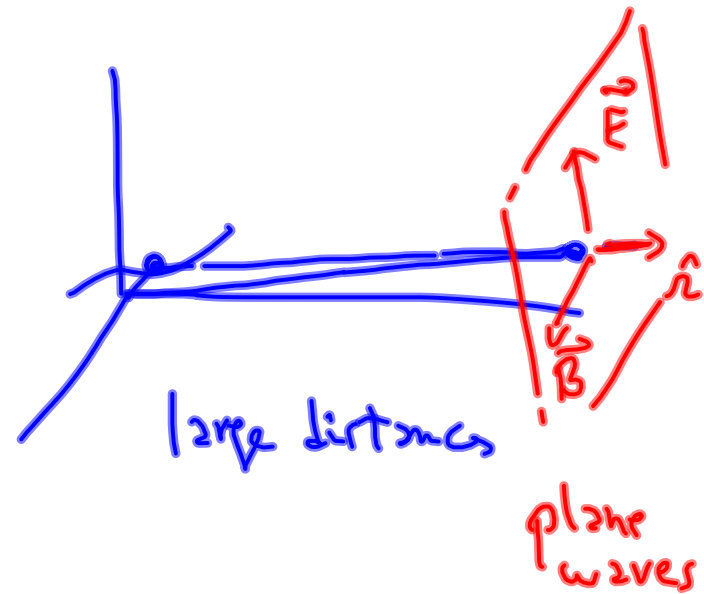
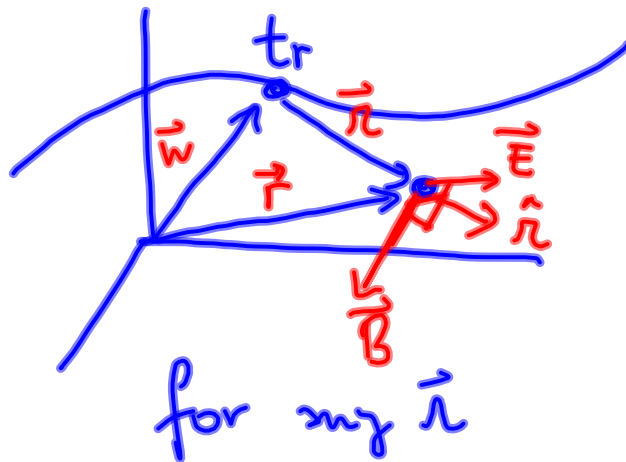
$$\vec{E}(\vec{r}, t) = \frac{q}{4\pi\epsilon_0 (\vec{\lambda} \cdot \vec{\lambda})^3} [\vec{\lambda} (c^2 - v^2) + \vec{\lambda} \times (\vec{\lambda} \times \vec{a})]$$

$$\vec{\lambda} = c \hat{n} - \vec{v}$$

$$\frac{1}{r}$$

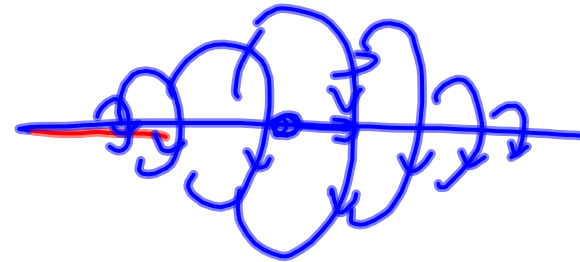
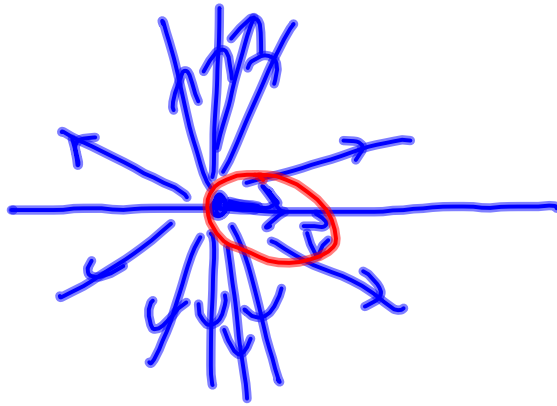
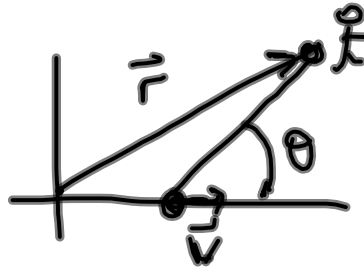
$$\frac{E \sim 1}{B \sim 1}$$

$$\vec{B} = \nabla \times \vec{A} = \frac{1}{c} (\hat{n} \times \vec{E})$$



Example

$$\left. \begin{array}{l} \vec{a} = 0 \\ \vec{w} = \vec{v}t \end{array} \right\} \rightarrow \vec{E} = \frac{q}{4\pi\epsilon_0} \cdot \frac{\vec{r} - \vec{v}t}{|\vec{r} - \vec{v}t|^3} \cdot \frac{1 - \frac{v^2}{c^2}}{\left(1 - \frac{v^2}{c^2} \sin^2 \theta\right)^{3/2}}$$



Power radiated by a point charge

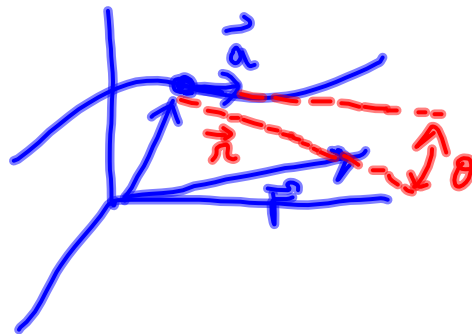


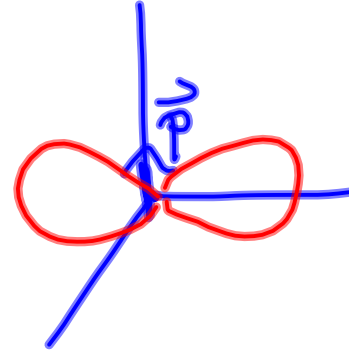
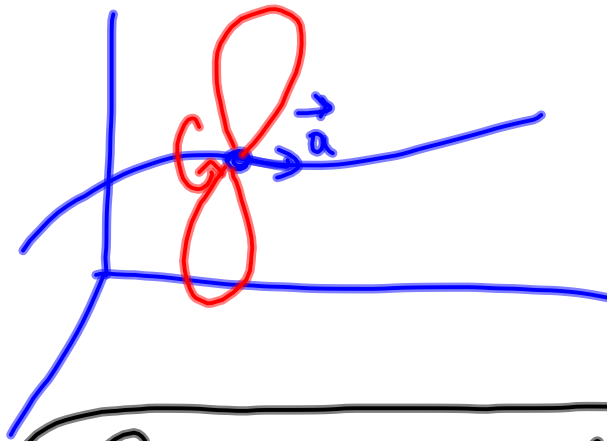
$$\vec{E}, \vec{B}$$

$$\vec{S} = \frac{1}{\mu_0 c} |\vec{E}|^2 \hat{r}$$

$$|\vec{E}| \cdot \frac{|\vec{E}|}{c}$$

Example: $\vec{v}=0, \vec{a} \neq 0$; $\vec{S} = \frac{1}{4\pi\epsilon_0} \cdot \frac{q^2}{4\pi c^3} \cdot \frac{a^2 \sin\theta}{r^2} \hat{r}$





$$P = \frac{1}{4\pi\epsilon_0} \cdot \frac{2}{3} \cdot \frac{q^2 a^2}{c^3} \quad \text{Larmor formula}$$