

3.1

$$\nabla^2 \Phi = 0$$

$$\Phi = U P Q$$

$\left[\frac{\partial}{\partial r} \dots \frac{\partial}{\partial \theta} \dots \frac{\partial}{\partial \phi} \right]$

$$Q = e^{\pm i m \phi}, \quad m = \text{integer}$$

$$\frac{d^2 U}{dr^2} - \frac{l(l+1)U}{r^2} = 0, \quad U = A r^{l+1} + B r^{-l}$$

$$\frac{d}{dx} \left[(1-x^2) \frac{dP}{dx} \right] + \left[l(l+1) - \frac{m^2}{1-x^2} \right] P = 0$$

$x = \cos \theta$

$$\underline{m = 0}$$

1. $l = 0$ or a positive integer

2. $P_0(x) = 1$

$$P_1(x) = x$$

$$P_2(x) = \frac{1}{2}(3x^2 - 1)$$

.....

$$x = \cos \theta$$

$$dx = -\sin \theta d\theta$$

3. $\int_{-1}^1 P_l'(x) P_l(x) dx = \frac{2 \delta_{ll'}}{2l+1}$

3.3 Problems with Azimuthal Symmetry



$V(\theta)$

$m=0$

$$\Phi = \frac{U(r)}{r} P(\theta) Q \stackrel{1}{=} =$$

$$= \sum_{l=0}^{\infty} \left(\frac{A_l r^{l+1} + B_l r^{-l}}{r} \right) P_l(\cos \theta)$$

$r < a$:

$B_l = 0$

$$\int_0^{\pi} \sin \theta d\theta$$

P_m

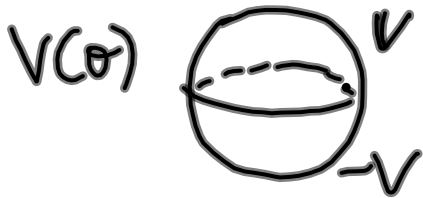
$r = a$:

$$V(\theta) = \sum_{l=0}^{\infty} A_l a^l$$

$$\int_0^{\pi} P_l(\cos \theta) P_m \sin \theta d\theta$$

orthog. relation

$$A_l = \frac{2l+1}{2a^l} \int_0^\pi d\theta \sin\theta P_l(\cos\theta) V(\theta)$$



3.5 $m \neq 0$

$$l = 0, 1, 2, 3, \dots$$

$$m = -l, -(l-1), \dots, 0, \dots, l-1, l$$

$$P_l^m(\cos\theta) \quad \Phi = \frac{U}{r} P_l^m Q$$

$$Y_{lm}(\theta, \phi) = \sqrt{\frac{2l+1}{4\pi} \frac{(l-m)!}{(l+m)!}} P_l^m(\cos\theta) e^{im\phi}$$

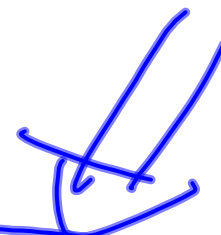
$$\int_0^{2\pi} d\phi \int_0^\pi \sin\theta d\theta Y_{l'm'}^*(\theta, \phi) Y_{lm}(\theta, \phi) = \delta_{ll'} \delta_{mm'}$$

$$Y_{00} = \frac{1}{\sqrt{4\pi}}$$

$$Y_{11} = -\sqrt{\frac{3}{8\pi}} \sin\theta e^{i\phi}$$

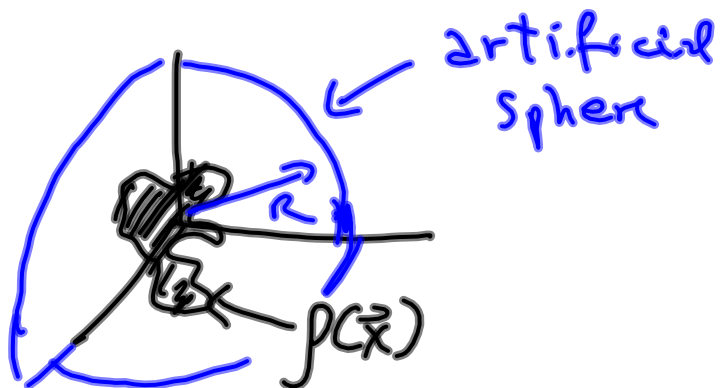
$$Y_{10} = \sqrt{\frac{3}{4\pi}} \cos\theta$$

$$Y_{20} = \sqrt{\frac{5}{4\pi}} \left(\frac{3}{2} \cos^2\theta - \frac{1}{2} \right)$$



$$\Phi(r, \theta, \phi) = \sum_{l=0}^{\infty} \sum_{m=-l}^l \left[A_{lm} r^l + B_{lm} r^{-l-1} \right] Y_{lm}(\theta, \phi)$$

4.1 Multipole Expansion



$$\Phi = \sum_{l,m} \left[\underline{B_{lm}} \frac{r^{-l-1}}{r} \underline{Y_{lm}(\theta, \phi)} \right]$$

↑ =

$\frac{1}{4\pi\epsilon_0} \frac{4\pi}{2l+1} \underline{q_{lm}}$

$$\Phi(\vec{x}) = \frac{1}{4\pi\epsilon_0} \int \frac{\rho(\vec{x}') d^3x'}{|\vec{x} - \vec{x}'|}$$

$$\frac{1}{|\vec{x} - \vec{x}'|} = 4\pi \sum_l \sum_m \frac{1}{2l+1} \frac{r_{<}^l}{r_{>}^{l+1}} Y_{lm}^*(\theta', \phi') Y_{lm}(\theta, \phi)$$

\uparrow \uparrow
 θ, ϕ θ', ϕ'

$r_{<} =$ smaller of $|\vec{x}| = r$ and $|\vec{x}'| = r'$
 $r_{>} =$ larger of $|\vec{x}|$ and $|\vec{x}'|$

outside sphere of radius R

$$\Phi = \frac{1}{4\pi\epsilon_0} \int \rho(\vec{x}') d^3x' = 4\pi \sum_{l,m} \frac{1}{2l+1} \frac{r'^l}{r^{l+1}} Y_{lm}^*(\theta', \phi') Y_{lm}(\theta, \phi)$$

$$q_{lm} = \int Y_{lm}^*(\theta', \phi') r'^l \rho(\vec{x}') d^3x'$$

$$q_{00} = \int \underbrace{Y_{00}^*}_{1/\sqrt{4\pi}} (r')^0 \rho(\vec{x}') d^3x' \stackrel{!}{=} \frac{1}{4\pi} q$$

$$q = \int \rho(\vec{x}') d^3x'$$

$$q_{11} = \int \underbrace{Y_{11}^*}_{-\sqrt{\frac{3}{8\pi}} \sin\theta' e^{-i\phi'}}_{\cos\phi' - i\sin\phi'} r' \rho(\vec{x}') d^3x'$$

$$x' = r' \sin\theta' \cos\phi'$$

$$y' = r' \sin\theta' \sin\phi'$$

$$= -\sqrt{\frac{3}{8\pi}} \int (x' - iy') \rho(\vec{x}') d^3x'$$

$$= -\sqrt{\frac{3}{8\pi}} (q_x - iq_y)$$

$$q_{10} = \sqrt{\frac{3}{4\pi}} q_z$$



$$\vec{P} \stackrel{\text{def}}{=} \int \vec{r}' \rho(\vec{x}') d^3x'$$