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Further classification of tensors.

Consider how a vector transforms upon the inversion transformation in 3D:

$$S: \{x^i\} \quad \text{and} \quad S': \{x'^i\} \quad x'^i = -x^i$$

$$M^i_j = \frac{\partial x'^i}{\partial x^j} = \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{pmatrix} \quad \det |M| = -1$$

Prototype vector:  $r^i$

$$r'^i = -r^i \quad \text{in component}$$

$$\vec{r} = (x, y, z) = (-x', -y', -z') = \vec{r}'$$

We see that  $\vec{r}$  is odd under inversion because its components change sign.

Now consider:

$$\bar{C} = \bar{A} \times \bar{B} \quad \bar{A}, \bar{B} \text{ vectors.}$$

In components:

$$C^i = A^j B^k - A^k B^j$$

If we change to  $S'$  with  $x'^i = -x^i$  we see that  $A'^i = -A^i$   $B'^i = -B^i$

but then  $C'^i = C^i$ ! The components do not change.

$C^i$  is not a vector. It is a pseudovector.

Vectors are also called polar vectors.  
Pseudovector are called axial vectors.

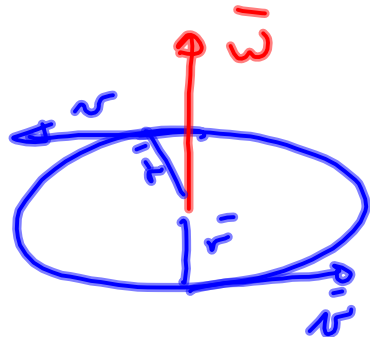
We see that  $C$  transforms as:

$$C'^i = |\det M| M^i_j C^j$$

if  $|\det M| = 1$  as in a rotation then  $C$  transforms like any vector

if  $|\det M| = -1$  (inversion, reflexions) then  $C$  does not transform as a vector.

There are many axial vectors in physics:



$$\vec{w} = \frac{\vec{r} \times \vec{n}}{r^2}$$

$\vec{w}$  is a pseudovector  
 $\vec{r}, \vec{n}$  are vectors.

Other examples:

$$\vec{L} = \vec{r} \times \vec{p} \quad \text{pseudovector.}$$

But:

$$\vec{n} = \vec{w} \times \vec{r} \quad \begin{array}{l} \text{polar} \swarrow \\ \text{axial} \end{array}$$

Let's write the cross product in tensor notation:

$$L_i = \sum_{j,k} \epsilon_{ijk} r^j p^k$$

How does  $\epsilon_{ijk}$  transform?

In 3D  $\epsilon_{ijk} = \epsilon^{ijk}$

$$\epsilon'^{ijk} = \frac{\partial x'^i}{\partial x^r} \frac{\partial x'^j}{\partial x^s} \frac{\partial x'^k}{\partial x^t} \epsilon^{rst} =$$

$$= M^i_r M^j_s M^k_t \epsilon^{rst} =$$

$$= \det M \epsilon^{ijk}$$

seen in previous lecture

If  $M$  is a rotation  $\det M = 1$  showing that  $\epsilon^{ijk}$  is isotropic.

isotropic means that the tensor has the same components in all systems of coordinates.

If  $\det M = -1$  as in an inversion then

$$\varepsilon^{ijk'} = -\varepsilon^{ijk} = \det M \varepsilon^{ijk}$$

Since the  $\det M$  appears in the transformation rule for  $\varepsilon^{ijk}$  then it is a **pseudotensor**.

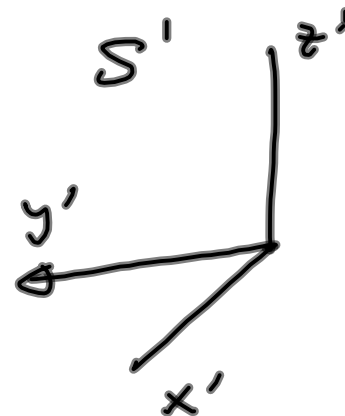
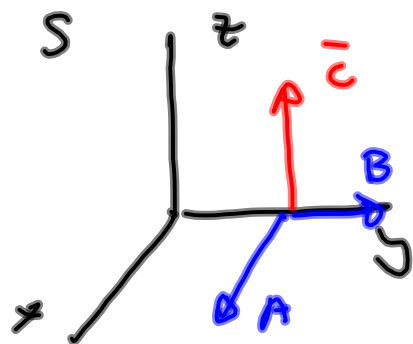
$$\varepsilon_{ijk} = \tilde{e}_i \cdot \tilde{e}_j \times \tilde{e}_k$$

$\hat{e}_i$  : ave vectors

$\hat{e}_j \times \hat{e}_k$  : pseudovector

$\hat{e}_i \cdot (\tilde{e}_j \times \tilde{e}_k)$  : pseudo tensor

Now consider reflexions in 3D:



$$x' = x$$

$$y' = -y$$

$$z' = z$$

$$M^i_j = \begin{pmatrix} 1 & & 0 \\ 0 & -1 & 0 \\ 0 & & 1 \end{pmatrix}$$

$$\det M = -1$$

$$\bar{C} = \bar{A} \times \bar{B}$$

We see that  $\bar{A}'$  and  $\bar{B}'$  look like reflected on the  $x-z$  plane but  $\bar{C}'$  seems to point in the opposite direction.

In general pseudotensors include  $\det M$  in their transformation. If  $\det M = -1$  then they transform differently than the same rank tensor.

Pseudoscalar:

$$S' = \det M S$$

Scalar

$$S' = S$$

Example:

$$S = \bar{A} \times \bar{B} \cdot \bar{C}$$

if  $\bar{A}, \bar{B}$  and  $\bar{C}$  are polar vectors then

$$S' = -S \text{ upon an inversion.}$$

$S$  is a pseudoscalar.



Notice:

scalar

$$S' = S$$

vector:

$$C'_i = \frac{\partial x^j}{\partial x'^i} C_j$$

Tensor of rank 2:

$$A'_{ij} = \frac{\partial x^k}{\partial x'^i} \frac{\partial x^l}{\partial x'^j} A_{kl}$$

pseudoscalar

$$S' = \det M S$$

pseudovector:

$$C'_i = \det M \frac{\partial x^j}{\partial x'^i} C_j$$

Pseudotensor of rank 2:

$$A'_{ij} = \det M \frac{\partial x^k}{\partial x'^i} \frac{\partial x^l}{\partial x'^j} A_{kl}$$

Properties of the cross-product (in 3D)

$$\bar{C} = \bar{A} \times \bar{B} \quad \bar{A}, \bar{B} \text{ are vectors.}$$

Let's see that  $\bar{C}$  is a pseudovector:

$$C^i = \varepsilon^{ijk} A_j B_k$$

$$C'^i = \varepsilon'^{ijk} A'_j B'_k = \det M \frac{\partial x'^i}{\partial x^r} \frac{\partial x'^j}{\partial x^s} \frac{\partial x'^k}{\partial x^t} \varepsilon^{rst}$$

$$\frac{\partial x^m}{\partial x'^i} A_m \frac{\partial x^n}{\partial x'^k} B_n = \det M \frac{\partial x'^i}{\partial x^r} \underbrace{\frac{\partial x^m}{\partial x'^j} \frac{\partial x^j}{\partial x^s}}_{\delta^m_s}$$

$$\frac{\partial x^n}{\partial x'^k} \frac{\partial x'^k}{\partial x^t} \varepsilon^{rst} A_m B_n \rightarrow \delta^n_t$$

$$= \det M \frac{\partial x^i}{\partial x^r} \delta_s^m \delta_t^n \epsilon^{rst} A_m B_n =$$

$$= \det M \frac{\partial x^i}{\partial x^r} \underbrace{\epsilon^{rmn} A_m B_n}_{C^r} = \det M \frac{\partial x^i}{\partial x^r} C^r$$

↘ pseudo vector.

## Dual Tensors

In some cases it is possible to develop a one to one correspondence between two tensors of different ranks. In this case the tensor of lower rank is called the dual tensor.

Example:

$C^{jk}$  is an antisymmetric tensor of rank 2 in 3D.

It has only 3 independent components that correspond to the number of components of a tensor of rank 1 in 3D.

Let's define:

$$C_i = \frac{1}{2} \epsilon_{ijk} C^{jk}$$

$$C^{jk} = \begin{pmatrix} 0 & C^{12} & C^{13} \\ -C^{12} & 0 & C^{23} \\ -C^{13} & -C^{23} & 0 \end{pmatrix}$$

$$\begin{aligned} C_1 &= \frac{1}{2} \epsilon_{1jk} C^{jk} = \frac{1}{2} (\epsilon_{123} C^{23} + \epsilon_{132} C^{32}) = \\ &= \frac{1}{2} (1 C^{23} + (-1) (-C^{23})) = C^{23} \end{aligned}$$

You can see that  $C_2 = C^{13}$  and  $C_3 = C^{12}$

Notice that if  $C^{jk}$  is a tensor then  $C_i$  is a pseudovector.

$$\text{Then } c^i = (c^{23}, c^{13}, c^{12})$$

Note: All the vectors in 3D physics that arise from a cross product of vectors are really duals of antisymmetrized direct products of the vectors that are cross-multiplied.

$$\vec{L} = \vec{r} \times \vec{p}$$

$$L_i = \epsilon_{ijk} r^j p^k = \frac{1}{2} \epsilon_{ijk} (r^j p^k - r^k p^j)$$

Notice that if  $N \neq 3$  this is not true:

$$N=2$$

$$T^{ij} = S^i R^j$$

$$A^{ij} = S^i R^j - S^j R^i = T^{ij} - T^{ji}$$

$A^{ij} = \begin{pmatrix} 0 & A \\ -A & 0 \end{pmatrix}$  one independent component  
 but a vector in  $N=2$  has  
 two components  $V^i = (V^1, V^2)$ .

Exercise: do the same for  $N=4$ .

Other uses of dual tensors:

1) consider  $V^{ijk} = A^i B^j C^k$   $A, B, C$ , vectors

Define:

$$V = \epsilon_{ijk} V^{ijk} = \epsilon_{ijk} A^i B^j C^k =$$

$$= A^i \underbrace{\epsilon_{ijk} B^j C^k}_{(\bar{B} \times \bar{C})_i} = \bar{A} \cdot (\bar{B} \times \bar{C})$$

$V$  is a pseudoscalar because  $A, B, C$  are vectors but

*Volume of the cell expanded  
by  $\bar{A}, \bar{B}$  and  $\bar{C}$ .*

$\epsilon_{ijk}$  is a pseudotensor.



Use of tensor notation to solve problems:

$$\bar{\nabla} \times (\bar{\nabla} \times \bar{A}) = ?$$

$$\bar{\nabla} \times (\bar{\nabla} \times \bar{A})$$

$\underbrace{\hspace{10em}}_{\epsilon_{ijk} \partial^j A^k}$

$$\epsilon^{rmi} \partial_m \epsilon_{ijk} \partial^j A^k$$

↓  
free index

I'll obtain  $V^r$

$$\begin{aligned}
 \epsilon^{rmi} \partial_m \epsilon_{ijk} \partial^j A^k &= \underbrace{\epsilon^{rmi} \epsilon_{ijk}}_{\substack{\epsilon^{imr} \\ \epsilon_{ijk}}} \partial_m \partial^j A^k = \\
 &= (\delta^r_j \delta^m_k - \delta^r_k \delta^m_j) \partial_m \partial^j A^k = \\
 &= \delta^r_j \delta^m_k \partial_m \partial^j A^k - \delta^r_k \delta^m_j \partial_m \partial^j A^k = \\
 &= \underbrace{\partial_k \partial^r A^k}_{\partial^r \partial_k A^k} - \partial_j \partial^j A^r = V^r
 \end{aligned}$$

(homework)

Then

$$\bar{V} = \bar{\nabla} \cdot (\bar{\nabla} \cdot \bar{A}) - \bar{\nabla}^2 \bar{A}$$