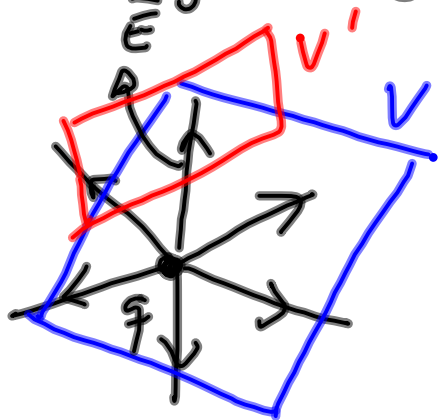


9 / 11

Divergence:

A vector field $\vec{G}(\vec{x})$ has non-zero divergence in a volume V if it has a singularity inside V :



$$\vec{\nabla} \cdot \vec{E} \propto q$$

$$\text{In } V \quad \vec{\nabla} \cdot \vec{E} \neq 0$$

but in V'

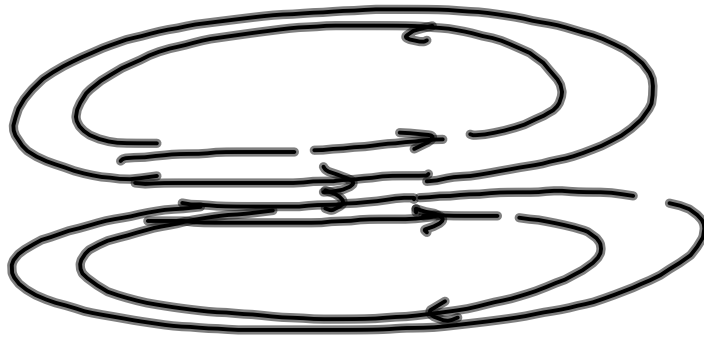
$$\vec{\nabla} \cdot \vec{E} = 0 \quad (\text{no charge, or singularity, in } V')$$

$\vec{G} = \vec{E}$ in this example.

If $\vec{\nabla} \cdot \vec{G} = 0$ everywhere \vec{G} is solenoidal. Example: \vec{B} (magnetic field).

$$\vec{\nabla} \cdot \vec{B} = 0$$

since there are not magnetic monopoles.



Solenoidal field
(no divergencies)

Useful expressions valid mostly in 3D.

$$1. \quad \bar{\nabla} \cdot \bar{r} = \bar{\nabla} \cdot (x \hat{x} + y \hat{y} + z \hat{z}) = 3$$

$$\parallel \quad \sum_i x^i \quad \left(\sum_i x^i = N \text{ in dimension } N \right)$$

$$2. \quad \bar{\nabla} \cdot (\bar{r} f(r)) = \sum_i \frac{\partial}{\partial x^i} [x^i f(r)] =$$

$$= \sum_i \left[\underbrace{\frac{\partial x^i}{\partial x^i}}_{\substack{\text{magnitude} \\ \text{of } r}} f(r) + x^i \frac{\partial f(r)}{\partial x^i} \right] = \sum_i f(r) + \sum_i x^i \frac{\partial f(r)}{\partial x^i}$$

$r = \left[\sum_i x_i^2 \right]^{1/2}$

$\frac{\partial r}{\partial x^i} = \frac{1}{2} \frac{2x^i}{\left[\sum_j x_j^2 \right]^{1/2}} = \frac{x^i}{r}$

$$= 3f(r) + \sum_i x^i \frac{\partial f(r)}{\partial r} \frac{\partial r}{\partial x^i} = 3f(r) \sum_i x^i \frac{\partial f(r)}{\partial r} \frac{x^i}{r} =$$

$$= 3f(r) + \frac{1}{r} \frac{\partial f(r)}{\partial r} \underbrace{\sum_i x_i^2}_{r^2} = \boxed{3f(r) + r \frac{\partial f(r)}{\partial r}}$$

$$3) \quad \bar{\nabla} \cdot (\underbrace{\vec{r}}_{f(r)} r^{n-1}) \overset{\text{using 2)}}{=} 3r^{n-1} + r \frac{\partial r^{n-1}}{\partial r} = 3r^{n-1} + (n-1)r r^{n-2}$$

$$= 3r^{n-1} + (n-1)r^{n-1} = \boxed{(n+2)r^{n-1}}$$

Curl

$$\vec{\nabla} \times \vec{V} = \begin{pmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_x & v_y & v_z \end{pmatrix} = \left(\frac{\partial v_z}{\partial y} - \frac{\partial v_y}{\partial z} \right) \hat{i} + \left(\frac{\partial v_x}{\partial z} - \frac{\partial v_z}{\partial x} \right) \hat{j} + \left(\frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} \right) \hat{k}$$

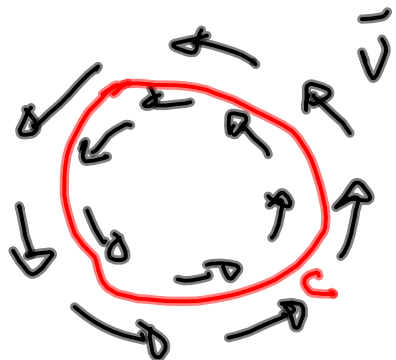
vector field

Examples:

$$\vec{B} = \vec{\nabla} \times \vec{A} \quad (\vec{A} \text{ vector potential})$$

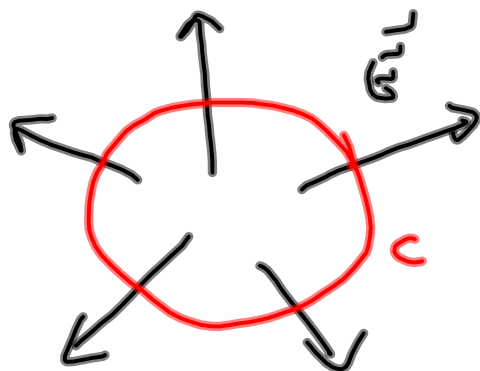
$$\vec{\nabla} \times \vec{E} = 0 \quad \text{for electrostatic field.}$$

Physical interpretation of the curl:



If a field \vec{V} has a finite circulation along a closedline c then $\nabla \times \vec{V} \neq 0$

$$\oint_c \vec{V} \cdot d\vec{l} \neq 0$$



$$\oint_c \vec{E} \cdot d\vec{l} = 0$$

Example:

$$\bar{\nabla} \times (\bar{r} f(r)) = ?$$

I'm going to use an expression from the back of the book that we are going to demonstrate later using tensors.

$$\bar{\nabla} \times (f \bar{V}) = f \bar{\nabla} \times \bar{V} + (\bar{\nabla} f) \times \bar{V}$$

In our case

$$\bar{\nabla} \times (f(r) \bar{r}) = f(r) \underbrace{\bar{\nabla} \times \bar{r}}_{\begin{matrix} \hat{x} & \hat{y} & \hat{z} \\ \partial_x & \partial_y & \partial_z \\ x & y & z \end{matrix}} = 0 + \underbrace{(\bar{\nabla} f) \times \bar{r}}_0 = 0$$

since $r = f(r) \Rightarrow \bar{\nabla} f \parallel \bar{r}$

Then $\bar{r} f(r)$ is irrotational.

Laplacian: $\nabla^2 = \bar{\nabla} \cdot \bar{\nabla}$ scalar

$$\nabla^2 \psi = \bar{\nabla} \cdot (\bar{\nabla} \psi) = \frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} + \frac{\partial^2 \psi}{\partial z^2}$$

↓ scalar
gradient: vector
Scalar

divergence: scalar

In tensor notation: $\bar{\nabla} = \partial_i$

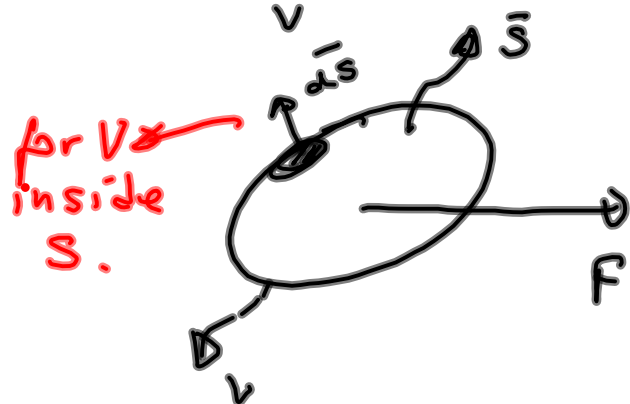
$$\nabla^2 = \partial_i \partial^i \equiv \frac{\partial^2}{\partial x_i^2}$$

Examples: $\bar{E} = -\bar{\nabla} \phi$ and $\bar{\nabla} \cdot \bar{E} = 0$ (if there are no charges)

$$0 = \bar{\nabla} \cdot \bar{E} = \bar{\nabla} \cdot (-\bar{\nabla} \phi) = -\nabla^2 \phi \Leftrightarrow \nabla^2 \phi = 0 \text{ (Laplace's equation),}$$

Divergence theorem or Gauss' Theorem:

$$\int_V \nabla \cdot \vec{F} dV = \oint_S \vec{F} \cdot d\vec{S}$$



$d\vec{S}$: magnitude of dS
(surface differential)
it points in the direction
 \perp to S and outside
the volume.

Examples: Gauss' Law: $\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}$ (Maxwell's eq.)

$$\oint_S \vec{E} \cdot d\vec{S} = \int_V \nabla \cdot \vec{E} dV = \int_V \frac{\rho}{\epsilon_0} dV = \frac{q}{\epsilon_0}$$

charge inside V
useful to get \vec{E} when it's constant on a surface.

2) Poisson's equation:

$$\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0} \quad \text{Maxwell}$$

in electrostatics $\vec{E} = -\nabla \phi$

$$\therefore \nabla \cdot \vec{E} = -\nabla^2 \phi = \frac{\rho}{\epsilon_0} \Rightarrow$$

$$\boxed{\nabla^2 \phi = -\frac{\rho}{\epsilon_0}}$$

Poisson's eq.

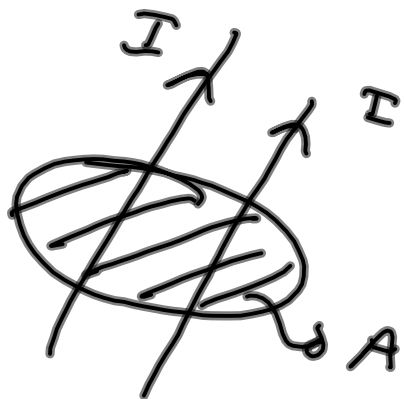
3) Ampère's law: (Stoke's theorem)

$$\int_S \nabla \times \vec{H} \cdot d\vec{S} = \int \vec{J} \cdot d\vec{S} = \vec{I} \text{ through surface}$$

$\nabla \times \vec{H} = \vec{J}$ (Maxwell's eq.)

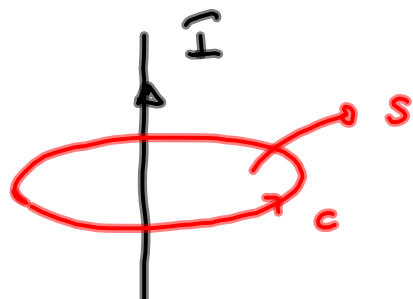
\vec{I} : current

$$\vec{J} = \frac{\vec{I}}{A} \rightarrow \text{area}$$



$$\vec{J} = \frac{\vec{I}}{A}$$

density of
current per
unit area.

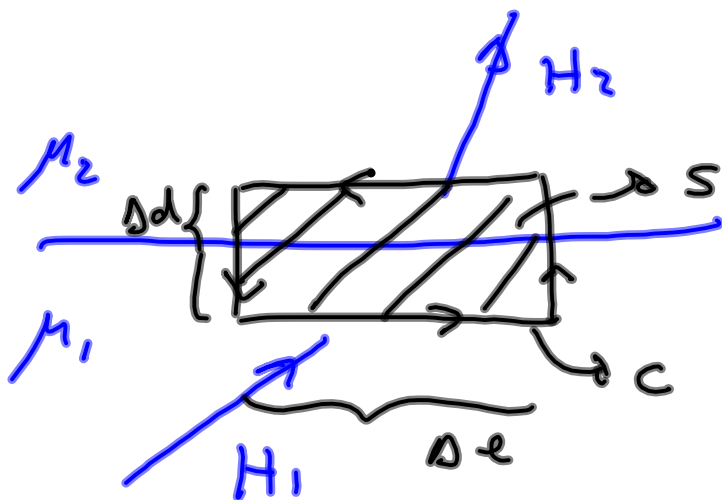


$$\oint_c \vec{H} \cdot d\vec{l} = \vec{I} \text{ through the surface.}$$

Stokes theorem

$$\oint_c \vec{H} \cdot d\vec{l} = \oint_S \nabla \times \vec{H} \cdot d\vec{S}$$

For homework.



What happens with the tangential component of \vec{H} across the surface?

$$\vec{K} = \lim_{\substack{\Delta d \rightarrow 0 \\ J \rightarrow \infty}} \vec{J} \cdot \Delta d$$

\vec{K}
linear density of current

analogous to point like dipole:
 $\vec{p} = \vec{d} q$ (real dipole)
 $\lim_{\substack{d \rightarrow 0 \\ q \rightarrow \infty}} \vec{d} q = \vec{p}$ (point like dipole).

Dirac Delta Function

$$\text{I} \dagger V = V(r)$$

$$r = \sqrt{x^2 + y^2 + z^2}$$

$$\bar{\nabla} V = \frac{\partial V}{\partial r} \hat{r}$$

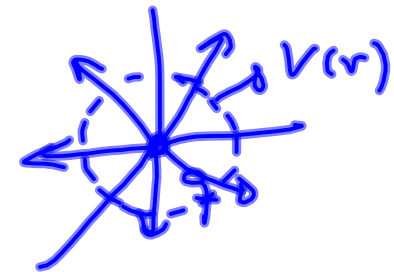
gradient \perp to equipotentials.

Consider a point charge $q = 4\pi\epsilon_0 \text{ (with a circled plus sign) } \text{ at the origin.}$

$$\bar{\nabla} \cdot \bar{E} = \frac{\rho}{\epsilon_0} \quad \bar{E} = -\bar{\nabla} \phi$$

$$\left[\bar{E} = \frac{q}{4\pi\epsilon_0 r^2} \hat{r} = \frac{4\pi\epsilon_0}{4\pi\epsilon_0} \frac{\hat{r}}{r^2} = \frac{\hat{r}}{r^2} \right]$$

$$\left[\phi = \frac{q}{4\pi\epsilon_0 r} = \frac{1}{r} \right]$$



Let's use Gauss' theorem:

$$\oint_S \vec{E} \cdot d\vec{S} = \int_V \vec{\nabla} \cdot \vec{E} dV = \int_V \frac{\rho(\vec{x})}{\epsilon_0} dV = \frac{q_{\text{encl}}}{\epsilon_0} \begin{cases} 4\pi\epsilon_0 \\ \text{or} \\ 0 \end{cases}$$

4π if q is inside V or 0 if not.

also

$$\begin{aligned} \oint_S \vec{E} \cdot d\vec{S} &= \oint \frac{\hat{r}}{r^2} \cdot d\vec{S} = \int_V \vec{\nabla} \cdot \left(\frac{\hat{r}}{r^2} \right) dV = \\ &= \int_V \vec{\nabla} \cdot \left(-\vec{\nabla} \left(\frac{1}{r} \right) \right) dV = - \int \nabla^2 \left(\frac{1}{r} \right) dV \end{aligned}$$

We can express the above result by introducing the delta "function" so that

$$\nabla^2 \left(\frac{1}{r} \right) = -4\pi \delta(\vec{r}) = -4\pi \delta(x) \delta(y) \delta(z)$$

with

$$\delta(x) = 0 \quad \text{if } x \neq 0$$

$$f(0) = \int_{-\infty}^{\infty} f(x) \delta(x) dx.$$