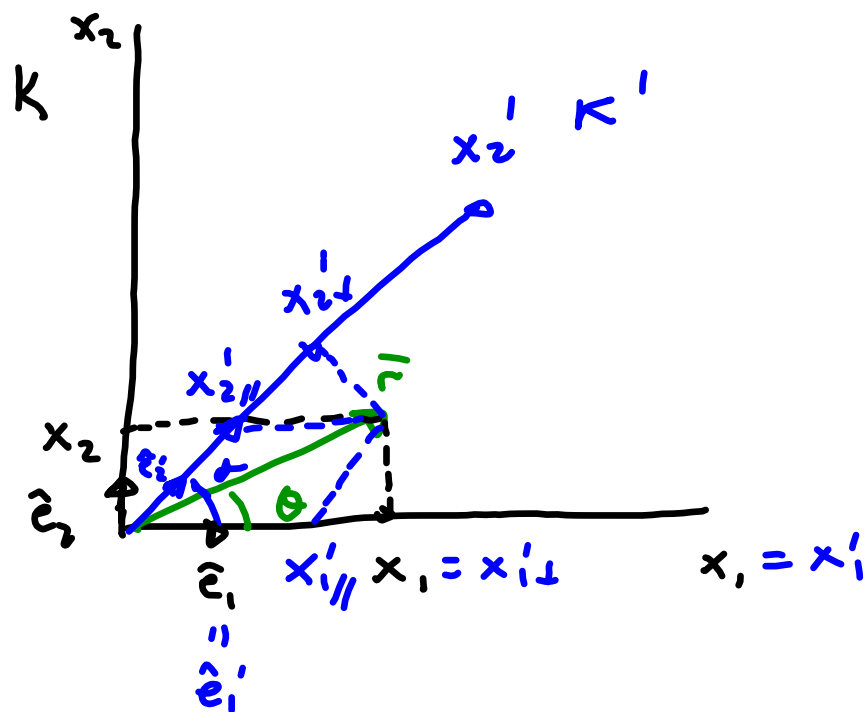


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$$\begin{matrix} \mathbb{H}_n & \kappa & \pi = x^j \hat{e}_j \\ \mathbb{H}_n & \kappa' & \pi = x'^j \hat{e}'_j \end{matrix}$$

Parallel components:

$$\begin{cases} x_1 = x'_{1//} + x'_{2//} \cos \alpha \\ x_2 = x'_{2//} \sin \alpha \quad (1) \end{cases}$$

$$\begin{cases} x'_{1//} = x_1 - x'_{2//} \cos \alpha = (1) \\ = x_1 - x_2 \cot \alpha \\ x'_{2//} = x_2 \csc \alpha \quad (2) \end{cases}$$

Perpendicular components

$$\begin{aligned} x'_{1\perp} &= x_1 \\ x'_{2\perp} &= x'_{2//} + x'_{1//} \cos \alpha \quad (2) \\ &= x_2 \csc \alpha + x_1 \cos \alpha - \\ &\quad - x_2 \frac{\cos^2 \alpha}{\sin \alpha} = \\ &= x_1 \cos \alpha + x_2 \left(\frac{1}{\sin \alpha} - \frac{\cos^2 \alpha}{\sin \alpha} \right) = \\ &= x_1 \cos \alpha + x_2 \sin \alpha \end{aligned}$$

$$\begin{cases} x'_{1\perp} = x_1 \\ x'_{2\perp} = \cos \alpha x_1 + \sin \alpha x_2 \end{cases}$$

$$\begin{cases} x_1 = x'_{1\perp} \\ x_2 = -\cot \alpha x'_{1\perp} + \csc \alpha x'_{2\perp} \end{cases}$$

How do $\{\hat{e}_i\}$ transform?

\hat{e}_i are covariant

$$\hat{e}'_1 = \hat{e}_1$$

$$\hat{e}'_2 = \cos \alpha \hat{e}_1 + \sin \alpha \hat{e}_2$$

In matrix form

$$(\hat{e}'_1, \hat{e}'_2) = (\hat{e}_1, \hat{e}_2) \underbrace{\begin{pmatrix} 1 & \cos \alpha \\ 0 & \sin \alpha \end{pmatrix}}_{A^i_j}$$

We know that

$$A^i_j = \frac{\partial x^i}{\partial x'^j} \equiv \frac{\partial x^i}{\partial x'^j}$$

→ contravariant

We see that $x''_i = x'^i$ in the oblique system.

$$\text{Then } M^i_j = \frac{\partial x'^i}{\partial x^j} = \frac{\partial x''_i}{\partial x^j} = \begin{pmatrix} 1 & -\cot\alpha \\ 0 & \csc\alpha \end{pmatrix}$$

$$\text{then: } x''_i = M^i_j x^j \text{ or } \begin{pmatrix} x''_1 \\ x''_2 \end{pmatrix} = \begin{pmatrix} \\ \end{pmatrix} \begin{pmatrix} x^1 \\ x^2 \end{pmatrix}$$

M

and

$$x'^i_{\perp} = A^j_i x^j \text{ or } (x'^1_{\perp}, x'^2_{\perp}) = (x_1, x_2) \begin{pmatrix} \phantom{x'^1_{\perp}} \\ \phantom{x'^2_{\perp}} \end{pmatrix}$$

A

$$\text{Notice that } AM = \mathbb{I} \Rightarrow A = M^{-1}$$

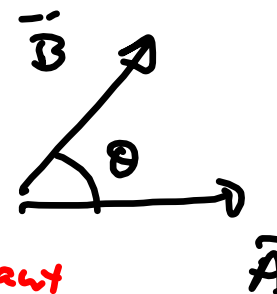
$$\text{or } A^i_j M^j_k = \delta^i_k$$

Vector operations

Scalar or dot product (particular case of "contraction").

You know that

$$\vec{A} \cdot \vec{B} = \sum_{i=1}^N A_i B_i = \sum_{i=1}^N B_i A_i = \vec{B} \cdot \vec{A}$$



As matrices:

$$\vec{A} \cdot \vec{B} = (a_1, \dots, a_N) \begin{pmatrix} b_1 \\ \vdots \\ b_N \end{pmatrix} = \sum_{i=1}^N a_i b^i = a_i b^i$$

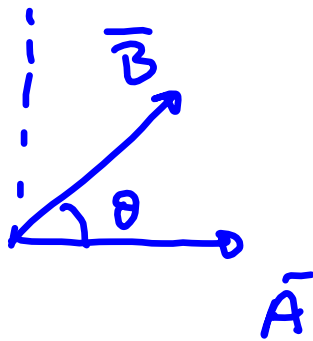
↑ contravariant
↙ covariant

Norm or length of a vector:

$$\bar{A} \cdot \bar{A} = a_i a^i = \sum_{i=1}^N a_i^2 = |\bar{A}|^2$$

Scalar or
tensor of
rank 0.

$$|\bar{A}| = (\bar{A} \cdot \bar{A})^{1/2} \equiv A \text{ scalar length.}$$



$$\bar{A} \cdot \bar{B} = A B_{\parallel} + A_{\perp} B_{\perp} = AB \cos \theta$$

\downarrow \downarrow
 $B \cos \theta$ 0

along \bar{A} direction

$$\cos \theta = \frac{\bar{A} \cdot \bar{B}}{AB} = \frac{a_i b^i}{(a_k a^k)^{1/2} (b_j b^j)^{1/2}}$$

Scalar product in oblique system:

$$\text{In } K: |\vec{r}|^2 = x_i x^i = x_1^2 + x_2^2$$

In K' (Oblique):

$$|\vec{r}'|^2 = x'_1 x'^1 + x'_2 x'^2 =$$

$$= (x_1 - x_2 \cotan \alpha) x_1 + x_2 \csc \alpha (x_1 \cos \alpha + x_2 \sin \alpha) =$$

$$= x_1^2 + x_2^2 = |\vec{r}|^2$$

using expressions for
 $x^i = f(x'^i)$ and
 $x'^i = f'(x^i)$

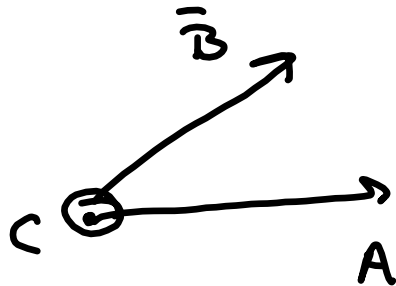
Warning:

$$x^i x_i \neq r^2 \quad x^i x^i = x_1^2 + \cotan^2 \alpha x_2^2 - 2x_1 x_2 \cotan \alpha + x_2^2 \csc^2 \alpha \neq r^2$$

$$x_i x_i \neq r^2$$

Vector or cross product:

$$\vec{C} = \vec{A} \times \vec{B}$$



$$C = AB \sin \theta$$

points out due to right hand rule.

In 3D:

$$\vec{C} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix} = (A_y B_z - A_z B_y) \hat{i} + (A_z B_x - A_x B_z) \hat{j} + (A_x B_y - A_y B_x) \hat{k}$$

We see that $\bar{\mathbf{B}} \times \bar{\mathbf{A}} = - \bar{\mathbf{A}} \times \bar{\mathbf{B}}$

Preview: tensor notation

$$C_i = \sum_{ijk} \epsilon_{ijk} A^j B^k \quad ijk : \text{in cyclic order}$$

ϵ_{ijk} : Levi-Civita tensor

- 0 if i, j or k are not all different
- 1 if i, j, k are in cyclic order
- 1 if i, j, k are not in cyclic order.

$$\epsilon_{112} = 0 \quad \epsilon_{231} = 1 \quad \epsilon_{213} = -1$$

$$C_i = \epsilon_{ijk} A^j B^k$$

then

$$\begin{aligned} C_x \equiv C_1 &= \underbrace{\epsilon_{123}}_1 A^2 B^3 + \underbrace{\epsilon_{132}}_{-1} A^3 B^2 = A^2 B^3 - A^3 B^2 = \\ &= A^y B^z - A^z B^y \end{aligned}$$

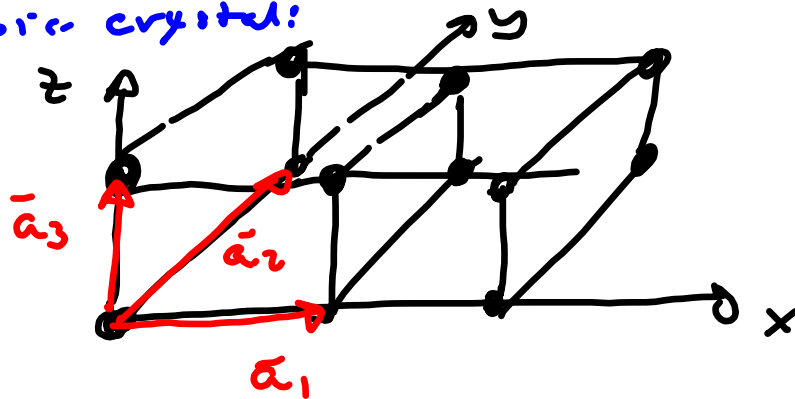
Vectors, covectors, reciprocal space and dual space.

Solid State Physics:

Crystals are form by arrays of atoms.

The position of any ion is obtained in terms of the basis vectors:

Cubic crystal:



$$\bar{a}_1 = d \hat{e}_1$$

$$\bar{a}_2 = d \hat{e}_2$$

$$\bar{a}_3 = d \hat{e}_3$$

d : lattice constant

$[d]$: length

$\{\bar{a}_i\}$ are linearly independent and the position \bar{R} of any ion is determined by a set of 3 integers:

$$\bar{R} = n_1 \bar{a}_1 + n_2 \bar{a}_2 + n_3 \bar{a}_3$$