

9/10

Last time:

$$\bar{\nabla} = \partial_\mu = \frac{\partial}{\partial x^\mu} \quad \text{covariant derivative}$$

and

$$\nabla^2 = \partial_\mu \partial^\mu \quad \text{Laplacian.}$$

$$\text{with } \partial^\mu = \frac{\partial}{\partial x_\mu} \quad \text{contravariant derivative.}$$

but we will learn about the metric tensor  $g_{\mu\nu}$  then we will use that  $\partial^\mu = g^{\mu\nu} \partial_\nu$ .

Examples:

$$\vec{E} = -\vec{\nabla}\phi \quad \text{and} \quad \vec{\nabla} \cdot \vec{E} = 0 \quad \text{if there are no charges.}$$

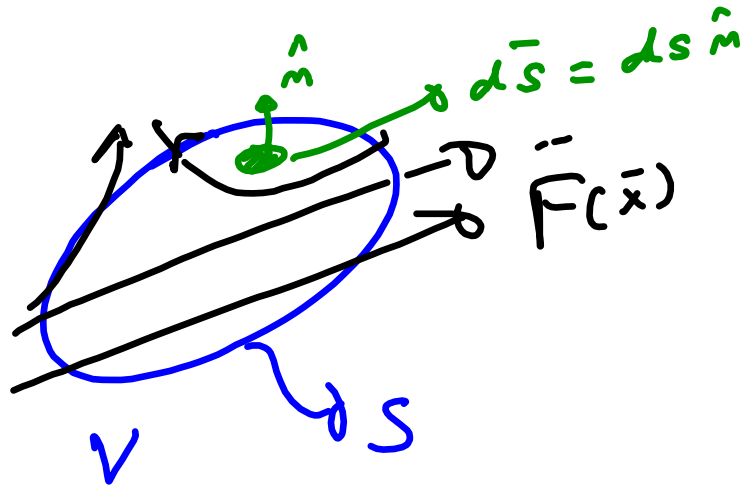
$$0 = \vec{\nabla} \cdot \vec{E} = \vec{\nabla} \cdot (-\vec{\nabla}\phi) = -\nabla^2\phi = 0$$

Then  $\nabla^2\phi = 0$  if no charges  
Laplace's equation.

We will learn techniques to solve it.

Divergence or Gauss' theorem:

$$\int_V \nabla \cdot \vec{F} \, dV = \oint \vec{F} \cdot d\vec{S}$$



Stoke's Theorem:

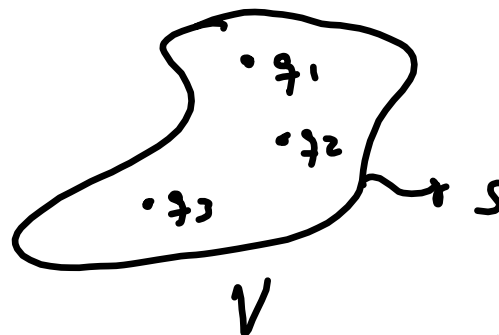
$$\int_S \nabla \times \vec{F} \cdot d\vec{s} = \oint_C \vec{F} \cdot d\vec{\ell}$$



Example:

1) Gauss' law:

$$\oint_S \vec{E} \cdot d\vec{S} = \frac{q_{\text{enclosed}}}{\epsilon_0}$$



Always valid but  
useful in symmetric  
situations.

$$\oint_S \vec{E} \cdot d\vec{S} = \int_V \underbrace{\nabla \cdot \vec{E}}_{\frac{\rho}{\epsilon_0} \text{ (Maxwell's)}} dV =$$

divergence theorem

$$\int \rho dV = q$$

$$= \int_V \frac{\rho}{\epsilon_0} dV = \frac{q_{\text{enclosed}}}{\epsilon_0}$$

2) Poisson's equation:

$$\bar{\nabla} \cdot \bar{E} = \frac{\rho}{\epsilon_0} \quad (\text{Maxwell 3rd.})$$

also  $\bar{E} = -\bar{\nabla} \psi$  (electrostatics)

$$\therefore \bar{\nabla} \cdot \bar{E} = -\nabla^2 \psi = \frac{\rho}{\epsilon_0} \Rightarrow \boxed{\nabla^2 \psi = -\frac{\rho}{\epsilon_0}}$$

Poisson's eq.  
(inhomogeneous  
differential  
equation)

3) Ampère's law:  $\nabla \times \vec{H} = \vec{J}$  (Maxwell's eq.).

$$\int_S \nabla \times \vec{H} \cdot d\vec{S} = \int_S \vec{J} \cdot d\vec{S} = \vec{I} \text{ through the surface.}$$

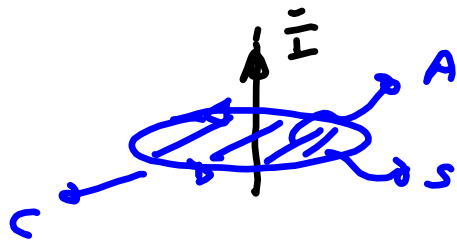
|| Stokes theorem

$$\oint_C \vec{H} \cdot d\vec{l}$$

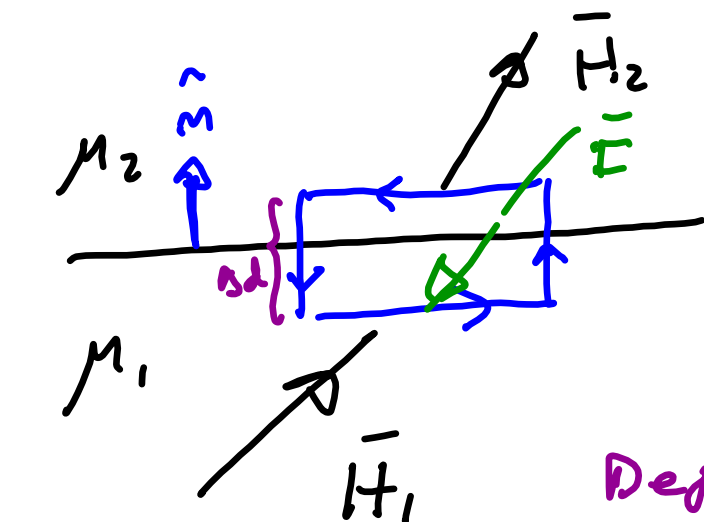
$\vec{J} = \frac{\vec{I}}{A}$  density of current  $\vec{I}$  through area  $A$ .

Then

$$\oint_C \vec{H} \cdot d\vec{l} = \vec{I} \text{ through the area}$$



In Hw #3 you will demonstrate the boundary conditions for the  $\vec{H}$ -field at an interface:



What happens with tangential component of  $\vec{H}$  across the interface?

$$\vec{J} = \frac{\vec{I}}{A}$$

Define:

$$\vec{K} = \lim_{\Delta d \rightarrow 0} \vec{J} \Delta d$$

linear density of current

Similar to

$$\vec{p} = \lim_{d \rightarrow 0} q d$$

$q \rightarrow \infty$   
point like dipole

$$q \overset{\circ}{\sim} \underset{\circ}{d} - q$$



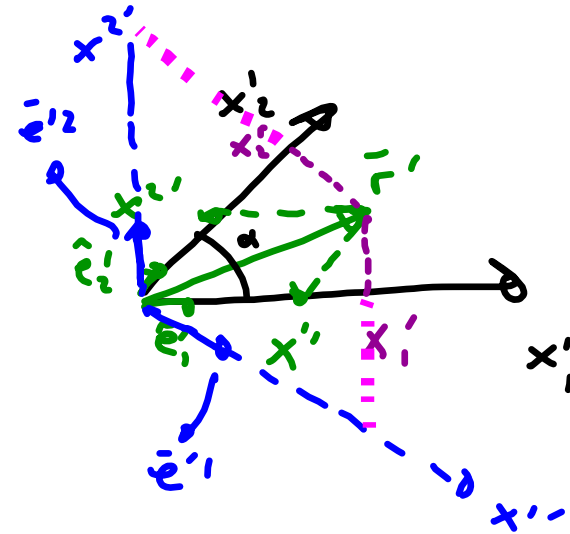
Also in HW #3:

You are going to show that in the oblique system:

$$\bar{r}' = x'^i \hat{e}_i \quad \text{in real space.}$$

and

$$\bar{r}' = x'_i \bar{e}^{i'} \quad \text{in dual space}$$



You will find out that

$$|\bar{e}^{i'}| = \text{cosec } \alpha \quad \text{then } |\bar{e}^{i''}| = 1 \quad \text{only if } \alpha = \pi/2.$$

## Dirac Delta "Function".

If  $V = V(r) \Rightarrow$  equipotentials are spheres,

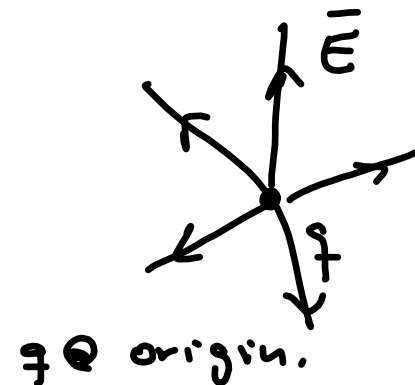
$$r = (x^2 + y^2 + z^2)^{1/2}$$

$$\vec{\nabla} V = \frac{\partial V}{\partial r} \hat{r} \quad \text{gradient is } \perp \text{ to equipotentials.}$$

Consider a point charge  $q = 4\pi\epsilon_0$

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0} \quad \vec{E} = -\vec{\nabla} \phi$$

$$\vec{E} = \frac{q}{4\pi\epsilon_0 r^2} \hat{r} = \frac{\hat{r}}{r^2} \text{ and } \phi = \frac{1}{r}$$



Now let's use Gauss' theorem for our charge  $q = 4\pi\epsilon_0$  at the origin:

$$\oint_S \vec{E} \cdot d\vec{s} = \int_V \vec{\nabla} \cdot \vec{E} dV = \int_V \frac{\rho(\vec{x})}{\epsilon_0} dV = \frac{q_{\text{enc}}}{\epsilon_0}$$

||

$$\vec{E} = -\nabla\phi = -\nabla\left(\frac{1}{r}\right)$$

||

$$\oint_S \frac{\hat{r}}{r^2} \cdot d\vec{s} = \int_V \vec{\nabla} \cdot \left(\frac{\hat{r}}{r^2}\right) dV =$$

$$= \int_V \vec{\nabla} \cdot \left(-\vec{\nabla}\left(\frac{1}{r}\right)\right) dV = - \int_V \nabla^2\left(\frac{1}{r}\right) dV$$

We define  $\nabla^2\left(\frac{1}{r}\right) = -4\pi\delta(\vec{r}) = -4\pi\delta(x)\delta(y)\delta(z)$  ②

$\left\{ \begin{array}{l} 4\pi \\ \text{or} \\ 0 \end{array} \right.$  ①  
 ↑ if origin in V.  
 ↓ if origin not in V.

Comparing ② with ① we see that

$$\int_V \delta(c\bar{r}) dV = \begin{cases} 1 & \text{if } \bar{r}=0 \in V \\ 0 & \text{if } \bar{r}=0 \notin V \end{cases}$$

Also notice that

$$\nabla^2 \left( \frac{1}{r} \right) = \begin{cases} 0 & \text{if } r \neq 0 \\ \text{diverges} & \text{if } r=0. \end{cases}$$

Properties of  $\delta(x)$ :

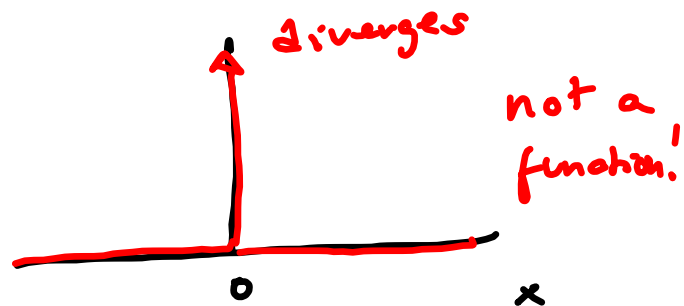
$$\delta(x) = 0 \quad \text{if } x \neq 0$$

$$f(0) = \int_{-\infty}^{\infty} f(x) \delta(x) dx$$

$$\text{If } f(x) = 1$$

$$\int_{-\infty}^{\infty} f(x) \delta(x) dx = \int_{-\infty}^{\infty} \delta(x) dx = f(0) = 1$$

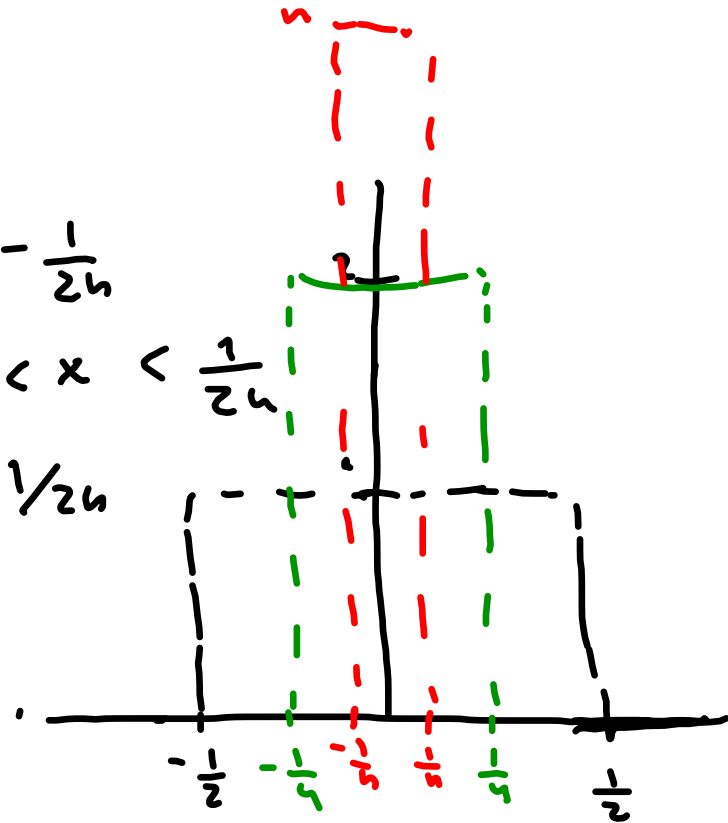
$$\text{Then } \int_{-\infty}^{\infty} \delta(x) dx = 1.$$



The  $\delta(x)$  is called a "distribution". It can be obtained as the limit of a sequence of functions called "support" functions but it is NOT a function itself.

Ex:

$$\delta_n(x) = \begin{cases} 0 & \text{if } x < -\frac{1}{2n} \\ n & \text{if } -\frac{1}{2n} < x < \frac{1}{2n} \\ 0 & \text{if } x > \frac{1}{2n} \end{cases}$$



Also!

$$\ast \delta_n(x) = \frac{n}{\sqrt{\pi}} e^{-n^2 x^2}$$

Gaussians

$\ast$  Lorentzians:

$$\delta_n(x) = \frac{n}{\pi} \frac{1}{1+n^2 x^2}$$

$$\ast \delta_n(x) = \frac{\sin nx}{\pi x} = \frac{1}{2\pi} \int_{-n}^n e^{ixt} dt$$

