

Lorentz Transf. along the x_1 direction

$$\begin{aligned} x_0' &= \gamma (x_0 - \beta x_1) & x_0' &= ct' \\ x_1' &= \gamma (x_1 - \beta x_0) & \beta &= v/c \\ x_2' &= x_2 & \gamma &= \frac{1}{\sqrt{1-\beta^2}} \\ x_3' &= x_3 \end{aligned}$$

$$\begin{aligned} x_0'^2 - (x_1'^2 + x_2'^2 + x_3'^2) & \stackrel{\text{L.T.}}{=} \\ &= x_0^2 - (x_1^2 + x_2^2 + x_3^2) \\ & \text{invariant} \end{aligned}$$

($c=c'$) Jackson

4-vectors :

In 3D,

$$\begin{pmatrix} x_1' \\ x_2' \\ x_3' \end{pmatrix} = \hat{A}_{3 \times 3} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

$$\begin{pmatrix} E_1' \\ E_2' \\ E_3' \end{pmatrix} = \hat{A}_{3 \times 3} \begin{pmatrix} E_1 \\ E_2 \\ E_3 \end{pmatrix}$$

$\vec{C} \cdot \vec{D}$ invariant

(A_0, A_1, A_2, A_3) is a 4-vector
if it transforms like
 (x_0, x_1, x_2, x_3)

$$A_0' = \gamma (A_0 - \beta A_1)$$

$$A_1' = \gamma (A_1 - \beta A_0)$$

$$A_2' = A_2$$

$$A_3' = A_3$$

$$\boxed{C \cdot D_0 - \vec{C} \cdot \vec{D}} \\ \text{invariant}$$

$$x'_0 = \gamma (x_0 - \beta x_1) = \underbrace{\gamma}_{\frac{\partial x'_0}{\partial x_0}} x_0 - \underbrace{\gamma\beta}_{\frac{\partial x'_0}{\partial x_1}} x_1, \quad x'_\alpha = \sum_{\beta} \frac{\partial x'^\alpha}{\partial x^\beta} x^\beta$$

Two types of 4-vectors:

Contravariant $\rightarrow A'^\alpha = \sum_{\beta} \frac{\partial x'^\alpha}{\partial x^\beta} A^\beta$

Covariant $\rightarrow B'_\alpha = \sum_{\beta} \frac{\partial x^\beta}{\partial x'^\alpha} B_\beta$

$$F'^{\alpha\beta} = \sum_{\gamma, \delta} \frac{\partial x'^\alpha}{\partial x^\gamma} \frac{\partial x'^\beta}{\partial x^\delta} F^{\gamma\delta}$$

Tensor of rank two.

The combination $\sum_{\alpha} B_{\alpha} A^{\alpha}$ is invariant under L. Transf.

Examples: $A^{\alpha} = (\Phi, \vec{A})$; $A_{\alpha} = (\Phi, -\vec{A})$
 $\partial^{\alpha} = \left(\frac{\partial}{\partial x^0}, -\nabla \right)$; $\partial_{\alpha} = \left(\frac{\partial}{\partial x^0}, \nabla \right)$

Lorentz gauge: $\sum_{\alpha} \boxed{\partial_{\alpha} A^{\alpha} = 0} = \frac{1}{c} \frac{\partial \Phi}{\partial t} + \nabla \cdot \vec{A}$

$g_{\alpha\beta} = \begin{pmatrix} 1 & & & \\ & -1 & & \\ & & -1 & \\ & & & -1 \end{pmatrix}$; $\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2 = \square = \sum_{\alpha} \partial_{\alpha} \partial^{\alpha}$
 D'Alembertian

$$\frac{1}{c^2} \frac{\partial^2 \vec{A}}{\partial t^2} - \nabla^2 \vec{A} = \frac{4\pi}{c} \vec{J} \Rightarrow \square \vec{A} = \frac{4\pi}{c} \vec{J}$$

$$\frac{1}{c^2} \frac{\partial^2 \Phi}{\partial t^2} - \nabla^2 \Phi = 4\pi \rho \Rightarrow \square \Phi = \frac{4\pi}{c} (\rho c)$$

$$\square A^\alpha = \frac{4\pi}{c} J^\alpha \quad J^\alpha = (\rho c, \vec{J})$$

$$\square A^\alpha = \frac{4\pi}{c} J^\alpha; \quad \partial_\alpha A^\alpha = 0$$

Now use \vec{E} and \vec{B}

$$F^{\alpha\beta} \equiv \partial^\alpha A^\beta - \partial^\beta A^\alpha$$

$$\vec{E} = -\frac{1}{c} \frac{\partial \vec{A}}{\partial t} - \nabla \Phi \rightarrow E_x = -\frac{1}{c} \frac{\partial A_x}{\partial t} - \frac{\partial \Phi}{\partial x} = -(\partial^0 A^1 - \partial^1 A^0)$$

$$\vec{B} = \nabla \times \vec{A} \rightarrow B_x = \frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} = -(\partial^2 A^3 - \partial^3 A^2)$$

$$F^{\alpha\beta} = \begin{pmatrix} 0 & -E_x & -E_y & -E_z \\ E_x & 0 & -B_z & B_y \\ E_y & B_z & 0 & -B_x \\ E_z & -B_y & B_x & 0 \end{pmatrix}; \quad \mathcal{F}^{\alpha\beta} = \begin{pmatrix} 0 & -B_x & -B_y & -B_z \\ B_x & 0 & E_z & -E_y \\ B_y & -E_z & 0 & E_x \\ B_z & E_y & -E_x & 0 \end{pmatrix}$$

Field Strength $\rho=0$ $\rho=1$ $\rho=2$ $\rho=3$ F^{32}

Dual Field Strength

Max. Eyr.

$$\left\{ \begin{array}{l} \sum_{\alpha} \partial_{\alpha} F^{\alpha\beta} = \frac{4\pi}{c} J^{\beta} \\ \sum_{\alpha} \partial_{\alpha} \mathcal{F}^{\alpha\beta} = 0 \end{array} \right. \left\{ \begin{array}{l} \beta=0 \rightarrow \nabla \cdot \vec{E} = 4\pi \rho \\ \beta=1,2,3 \rightarrow \nabla \times \vec{B} - \frac{1}{c} \frac{\partial \vec{E}}{\partial t} = \frac{4\pi}{c} \vec{J} \\ \beta=0 \rightarrow \nabla \cdot \vec{B} = 0 \\ \beta=1,2,3 \rightarrow \nabla \times \vec{E} + \frac{1}{c} \frac{\partial \vec{B}}{\partial t} = 0 \end{array} \right. \text{M.Eyr.}$$

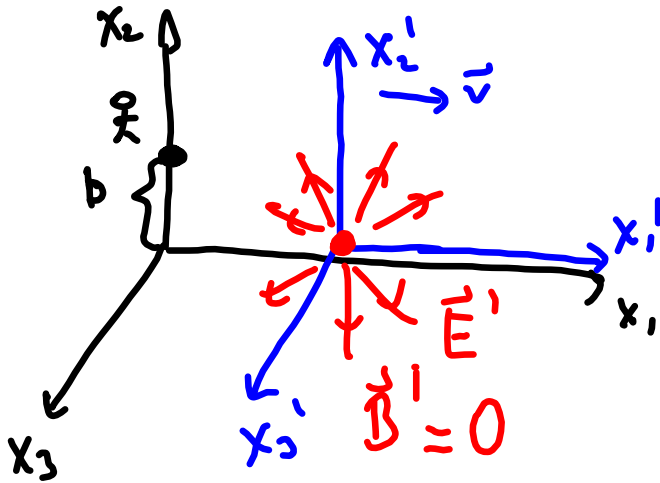
Since \vec{E} and \vec{B} are part of $F^{\alpha\beta}$, and we know how $F^{\alpha\beta}$ transforms, we know the new \vec{E}' and \vec{B}' .

$$F'^{\alpha\beta} = \left[\frac{\partial x'^{\alpha}}{\partial x^{\gamma}} \frac{\partial x'^{\beta}}{\partial x^{\delta}} F^{\gamma\delta} \right]$$

↑ contains \vec{E} and \vec{B}

contains \vec{E}' and \vec{B}'

Sec. 11.10 Jackson



$$E_1 = E'_1 \quad B_1 = \cancel{B'_1}$$

$$E_2 = \gamma(E'_2 + \beta \cancel{B'_3}), \quad B_2 = \gamma(\cancel{B'_2} - \beta \cancel{E'_3})$$

$$E_3 = \gamma(\cancel{E'_3} - \beta \cancel{B'_2}); \quad B_3 = \gamma(\cancel{B'_3} + \beta E'_2)$$

$$\begin{array}{ll}
 E_1 \neq 0 & B_1 = 0 \\
 E_2 \neq 0 & B_2 = 0 \\
 E_3 = 0 & B_3 \neq 0
 \end{array}$$

